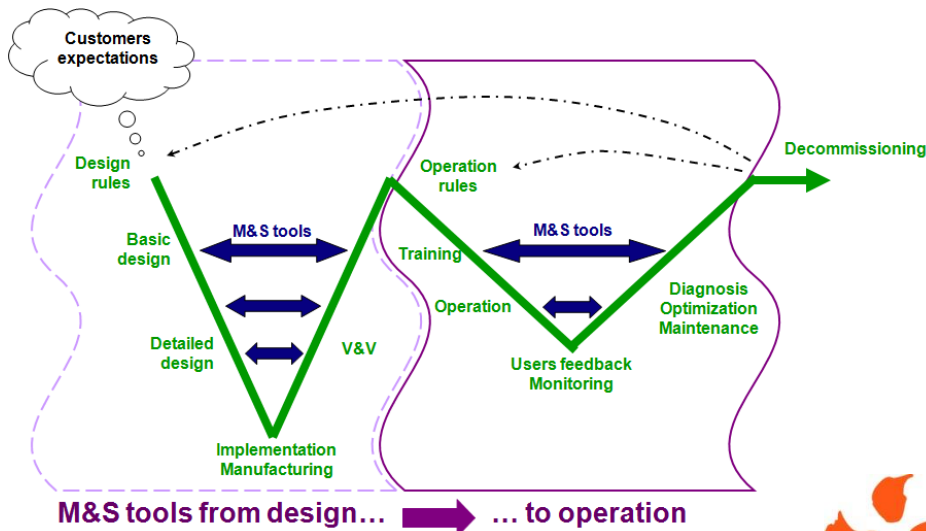




# ITEA 2

INFORMATION TECHNOLOGY FOR EUROPEAN ADVANCEMENT



## From Modelica models to dependability analysis

Marc Bouissou (EDF)  
Xavier de Bossoreille (DLR)



Robotics and  
Mechatronics Center

LMCS 2015



# Industrial challenge

---

- Separation of design and dependability analysis workflows
- Consequences:
  - The same information is input twice
  - Consistence is not guaranteed
  - Long delay between the two kinds of studies => no possibility of feedback, except for very serious issues
- Existing attempts to link design models to dependability:
  - Limited to fault tree production (+ FMEA)
  - Rely on a simple algorithm (assembly of FT parts, not a true *generation*), works for control systems but not for physical systems
  - No storage of *generic* reliability models

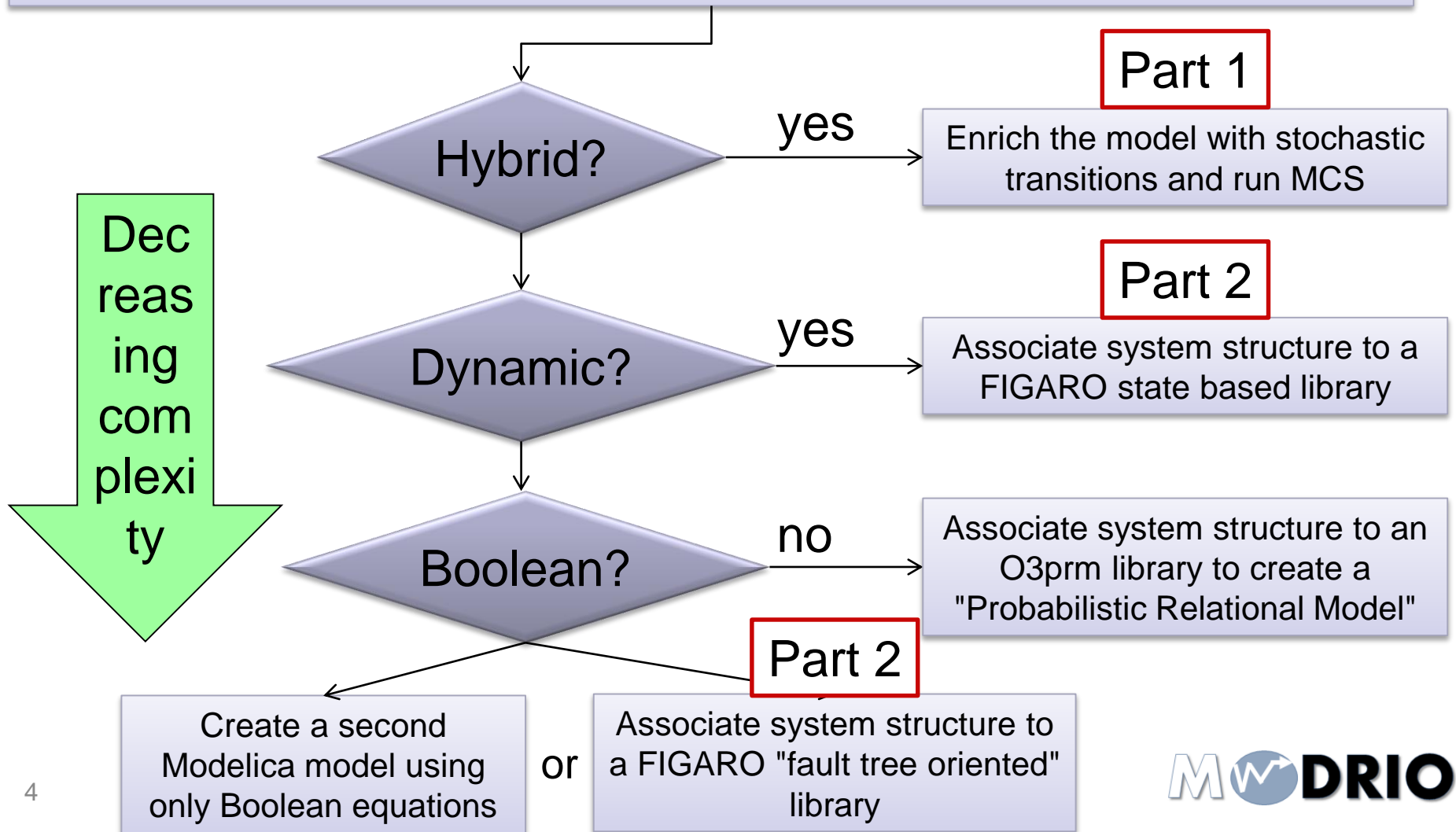
# Modelica and Figaro: two DSLs

---

- **Modelica: system design and functional validation**
  - Deterministic physical models: algebraic and differential equations (DAE)
  - Object oriented
  - Declarative and procedural parts
  - Supported by a large number of tools (open source or commercial)
- **Figaro: system dependability analysis**
  - Discrete stochastic models: states and stochastic transitions
  - Object oriented
  - Declarative (based on occurrence and interaction rules)
  - Supported by the KB3 platform (partly free. Should be open source soon)

# Various ways to derive stochastic models from Modelica models

Need for a reliability/availability analysis of a system already modeled in Modelica

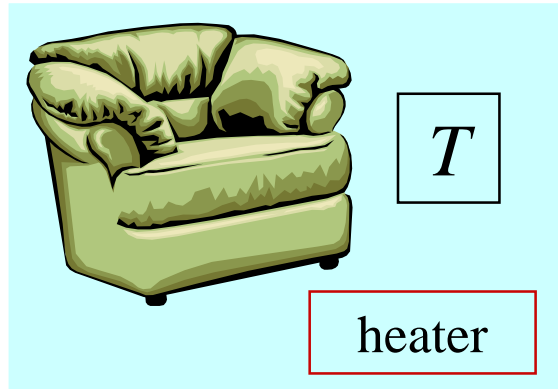


# Outline of part 1

---

- Introduction of stochastic transitions in Modelica
  - A simple test case
  - Modeling it using state machines
- Two more complex examples
- Perspectives

# The "Heated room" test case

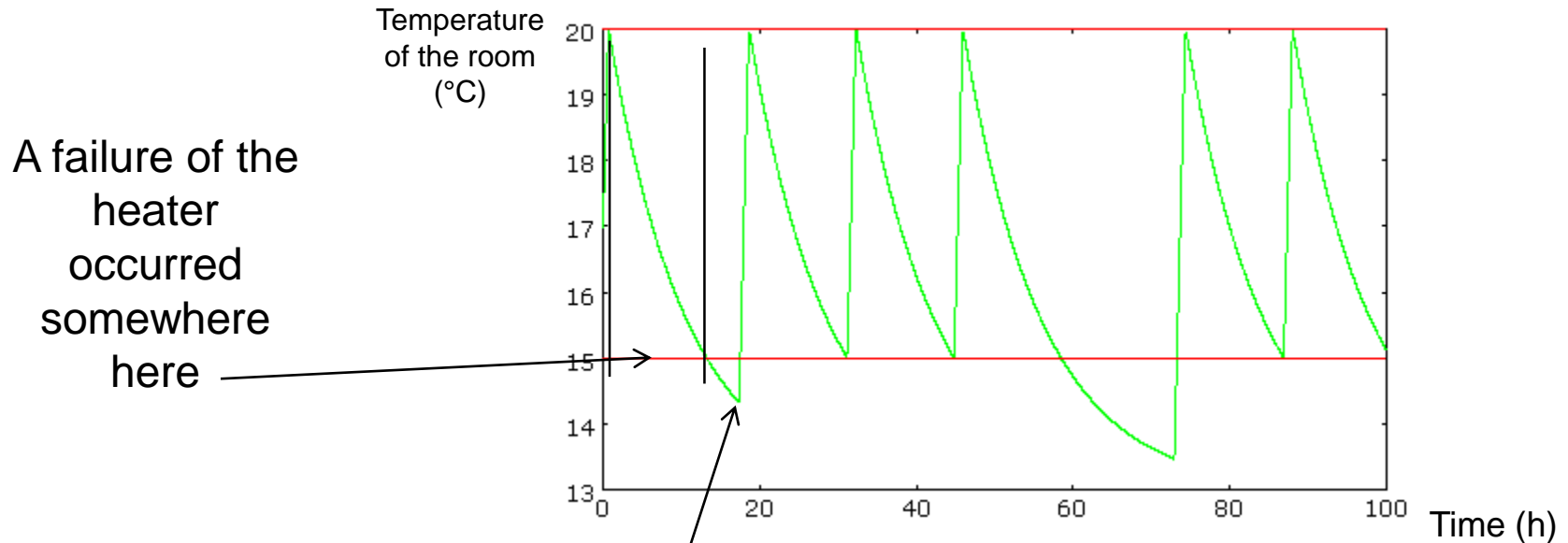


$T_E$  External temperature

Heater:

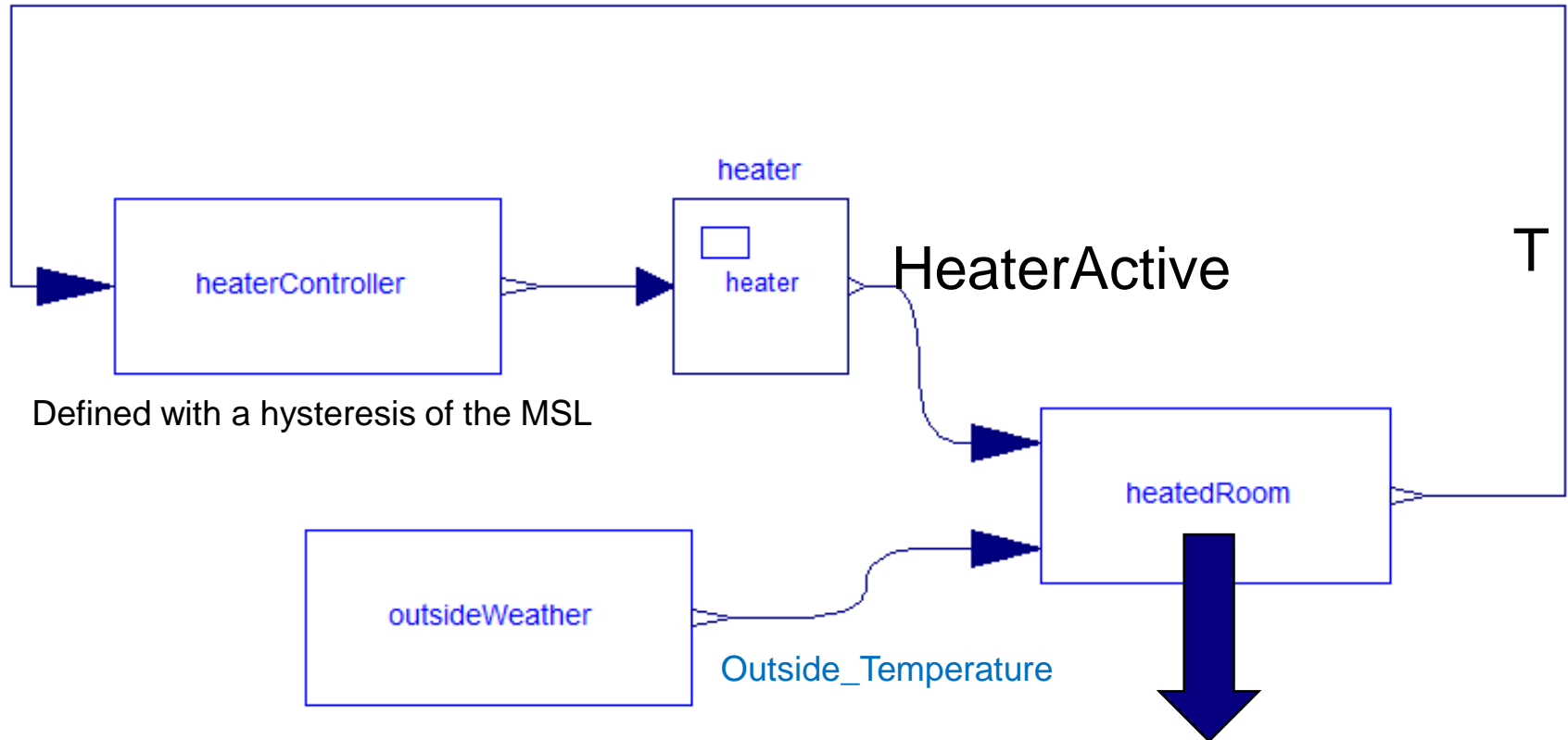
- on at  $T_{min}$ , off at  $T_{max}$
- **subject to random failures and repairs**
- exponential distributions for times to failure and times to repair

# An example of single (random) trajectory of $T$



This is a PDMP:  
 Piecewise Deterministic Markov Process

# Modelica model: structure



Defined with a hysteresis of the MSL

## equation

$$\text{der}(T) = \text{CoeffHeaterController} * \text{HeaterActive} + \text{CoeffOutsideTemperature} * (\text{Outside\_Temperature} - T);$$



# The heater: a first model

## algorithm

```

when initial() then
  F := seed; //each calculation of F will yield a pseudo random number
  in [0,1]
end when;
// Attention: the two following rules must not be merged in a single one!
when initial() then //calculating the first random working time
  F := mod(a*F+c, m);
  x := F / m;
  X:= (-log(1-x))/lambda;
end when;
when working then //random draw of the next working time
  F := mod(a*F+c, m);
  x := F / m;
  X:= (-log(1-x))/lambda;
end when;
// X is the working time
when working and (time - starttime_working) > X then
  working := false;
  starttime_notworking := time;
end when;

```

.... Similar instructions for repairs

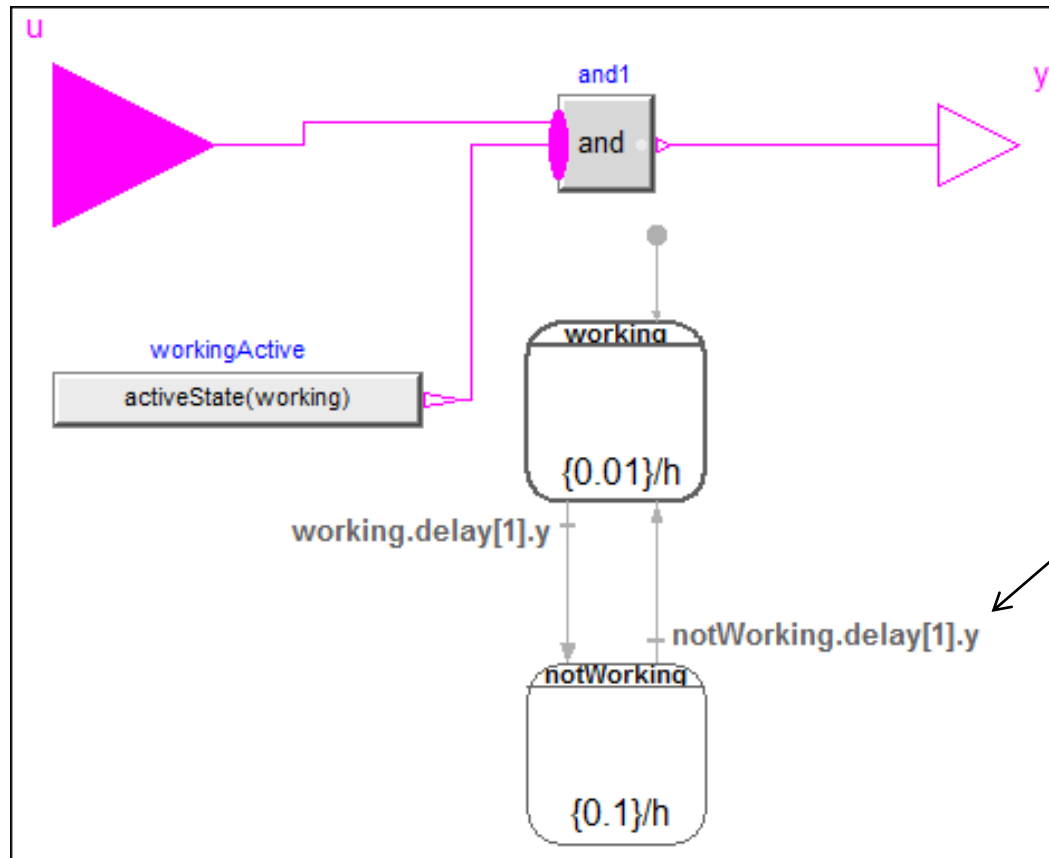
```

// Input-output relation
equation
if working then
  y = u;
else
  y = 0.;
end if;

```

Very cumbersome and error prone!

# The heater (in Modelica 3.3)



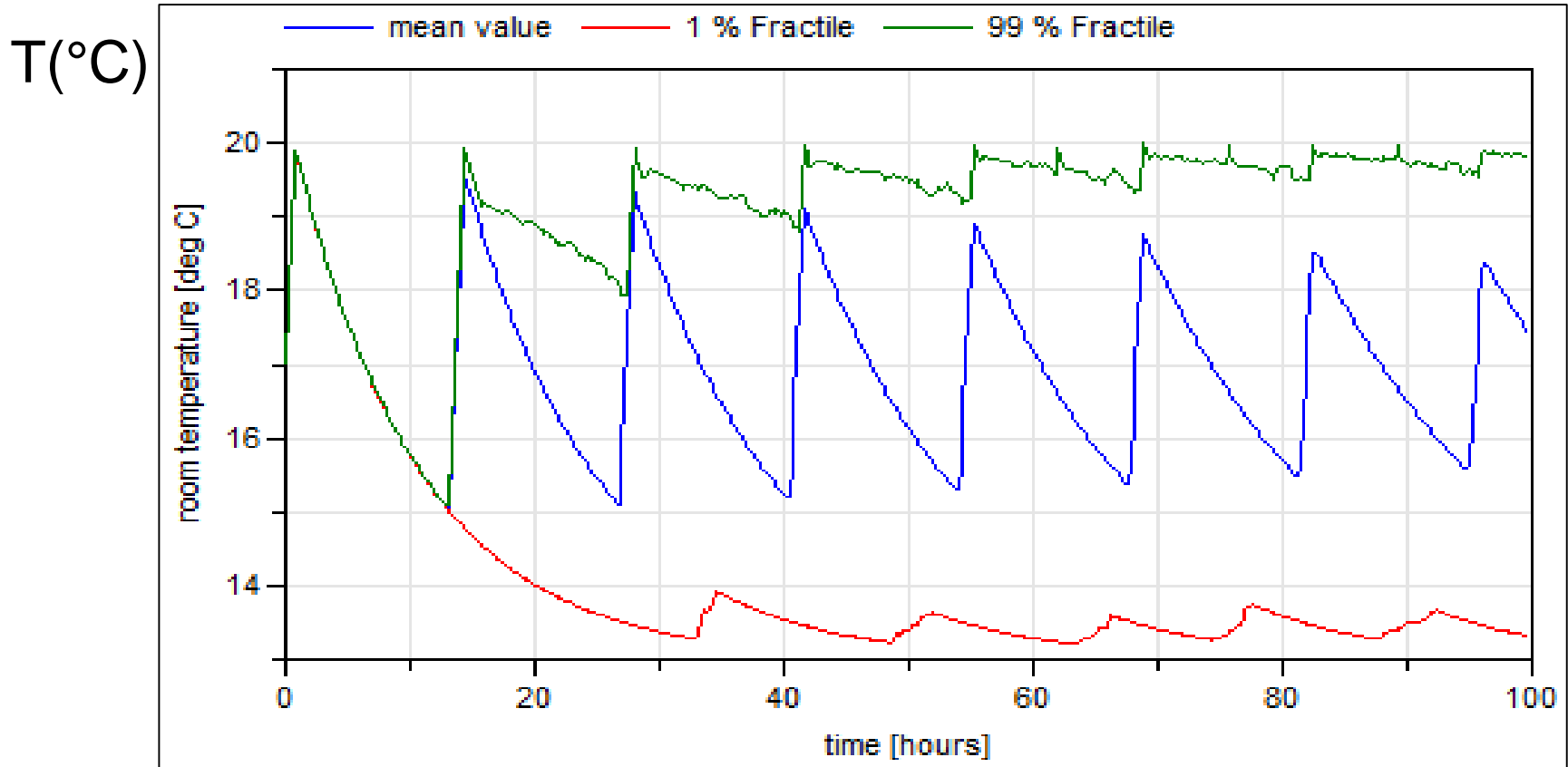
Essentially the same principles as what was shown on slide "Heater: a first model", but taking advantage of abstraction mechanisms provided by Modelica.

The user does not have to write any code

We use a **continuous time** state machine to describe the random behavior of the heater (only available in Dymola, cf. *Modelica extensions for multi-mode DAE systems*, Elmqvist, Mattsson and Otter, 2014)

# Results: Temperature (10000 random trajectories)

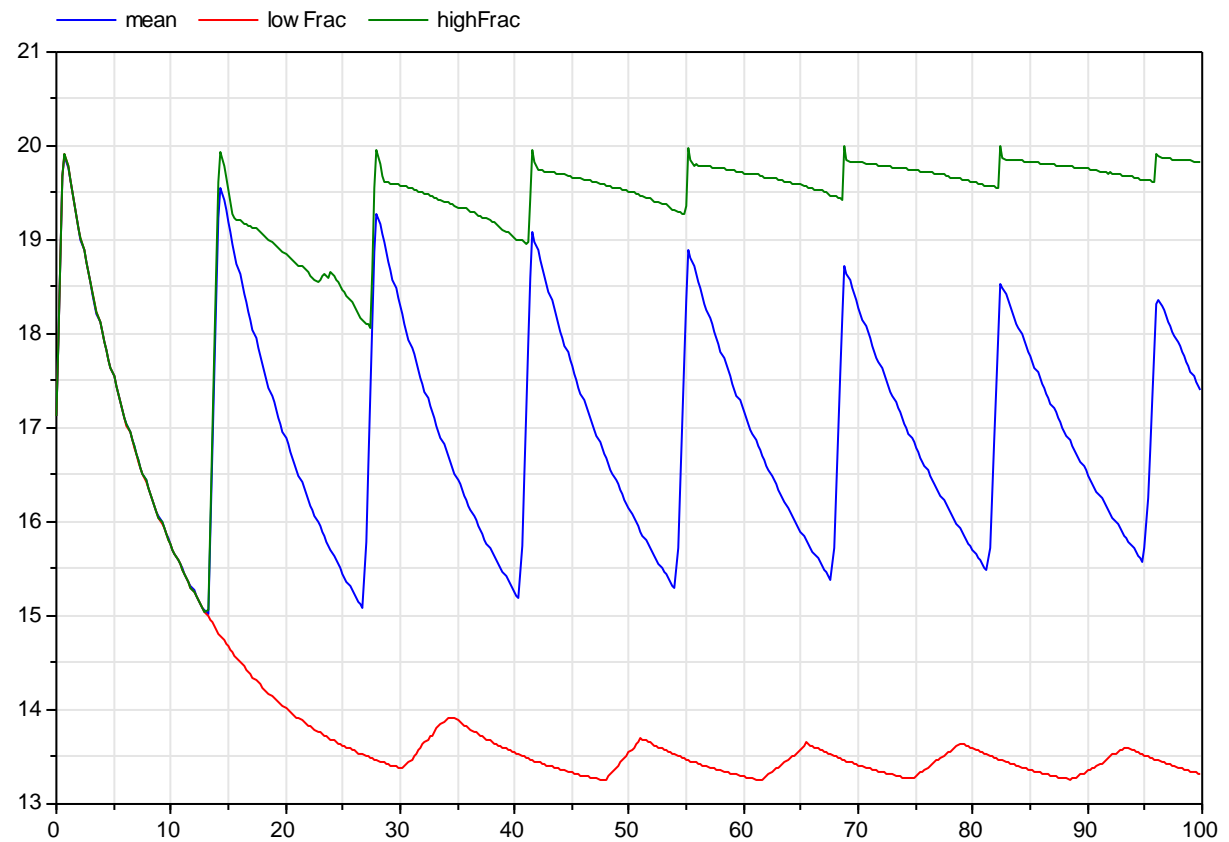
Presentation at DCDS 2015



time (h)

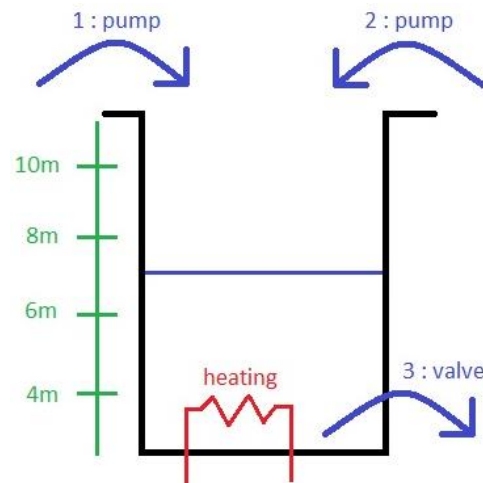
# Results

- Heated-room
- 1 000 000 sim
- 1h30



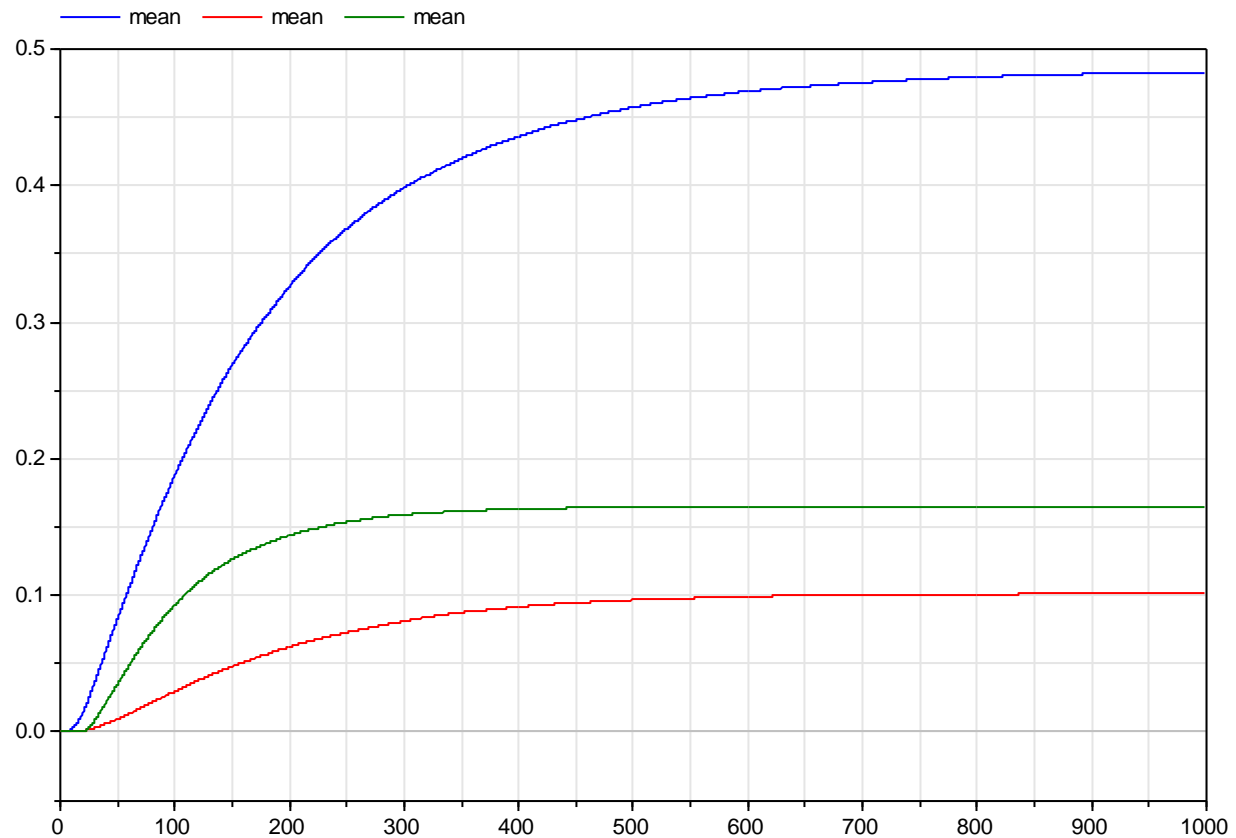
## Ex 2 : heated-tank

- Tank with 2 pumps and 1 valve
- Failure rates dependent on temperature
- 2 tied continuous variables : temperature and level
- A test case solved with dozens of methods in the literature!



# Results

- Heated-tank
- 100 000 sim
- 2h15
- Zhang et al. :  
1 min 30s  
or  
23h



## Conclusion

---

- 3 complementary test cases were solved
- Random state machines work... in Dymola
- Monte Carlo works and is fairly efficient
- Anyway, faster than some other general\* methods

\*General = that do not use analytical solutions for DAE

# Perspectives

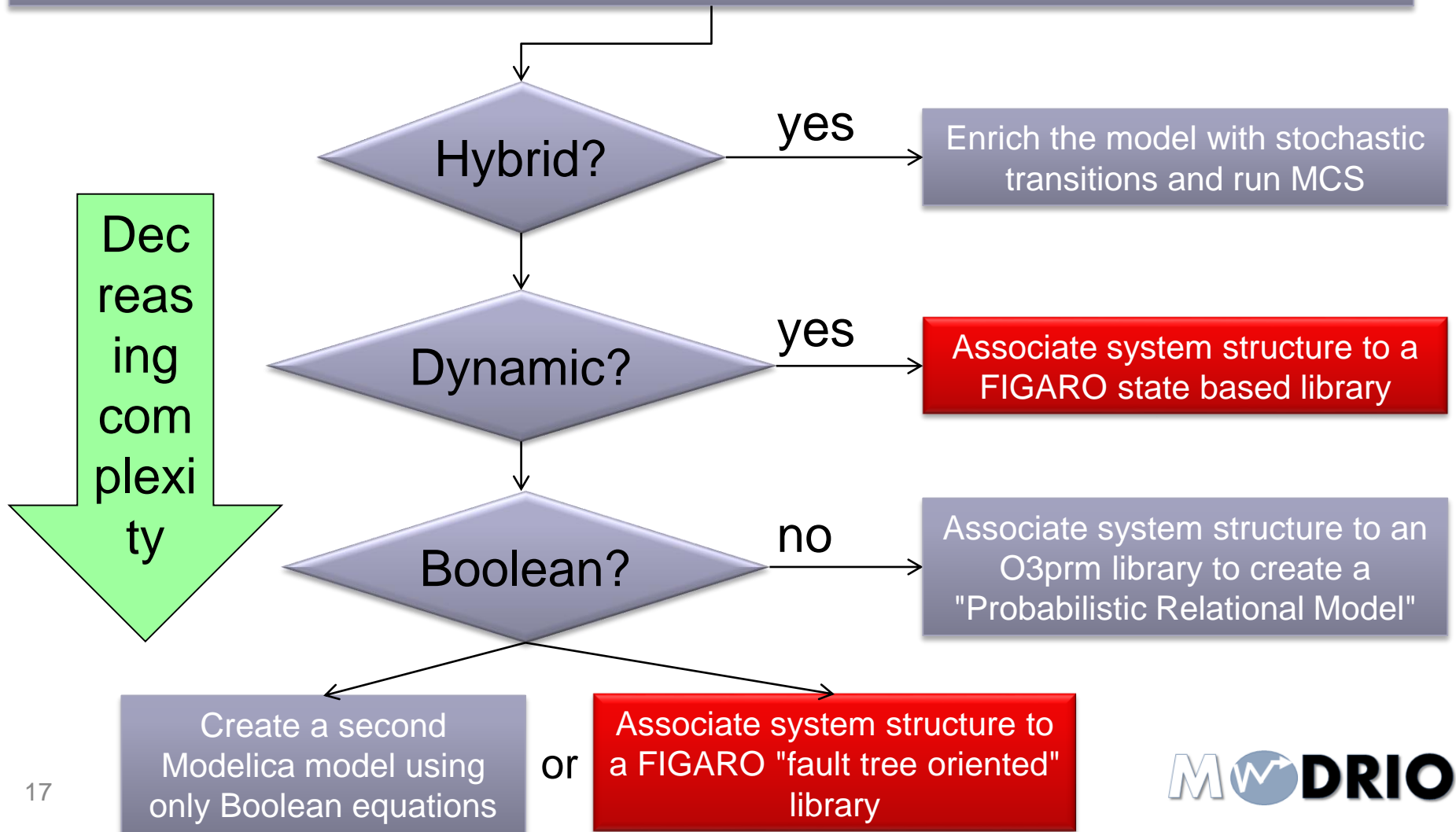
---

- Apply those principles to a complex system: a data center with electrical supplies, thermohydraulic cooling system
- Requires the extension of components models with stochastic state machines to represent failures, repairs, reconfigurations...
- Refine the Monte Carlo function
- **Convince the Modelica association to introduce "native" stochastic transitions in Modelica!**

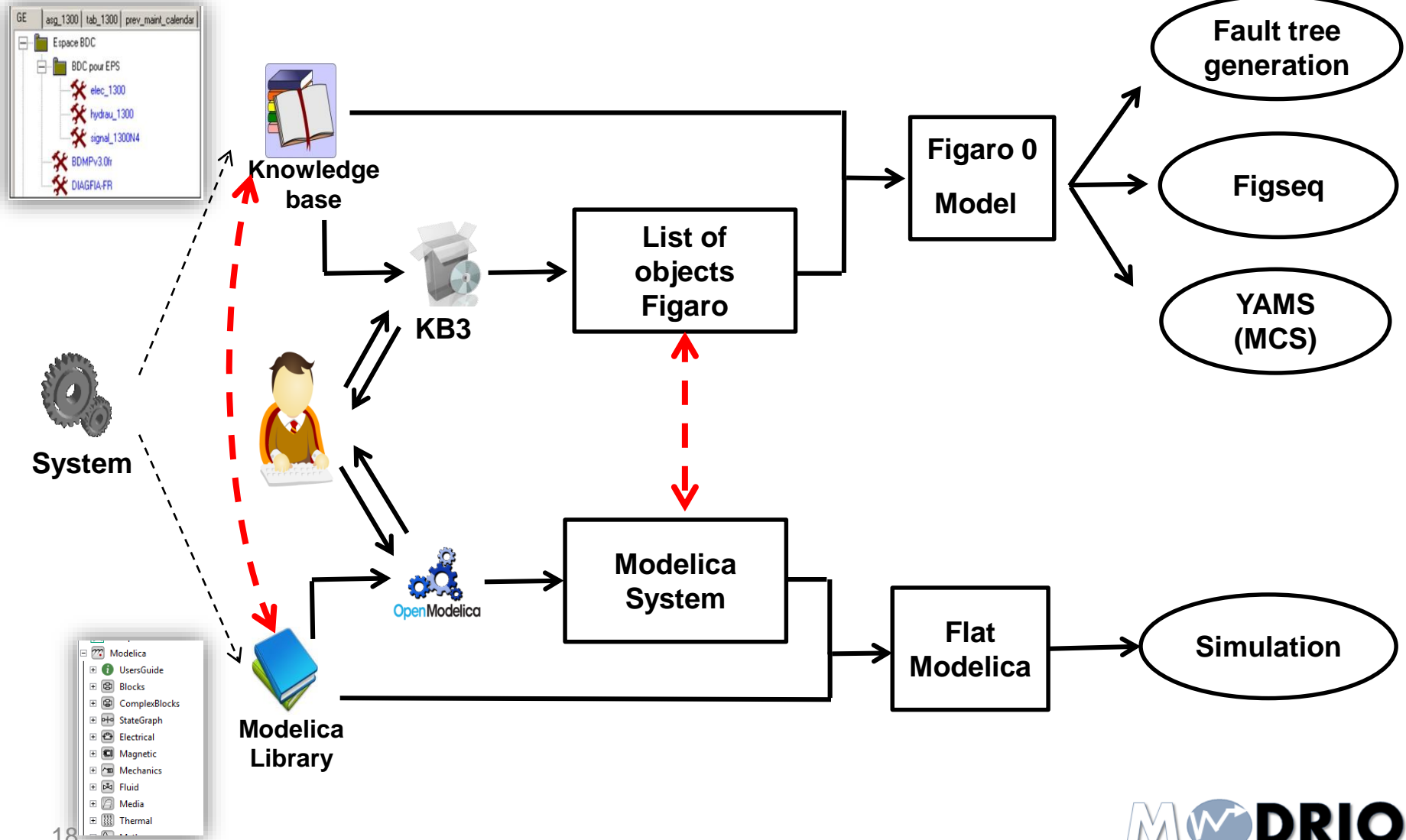


# Various ways to derive stochastic models from Modelica models

Need for a reliability/availability analysis of a system already modeled in Modelica

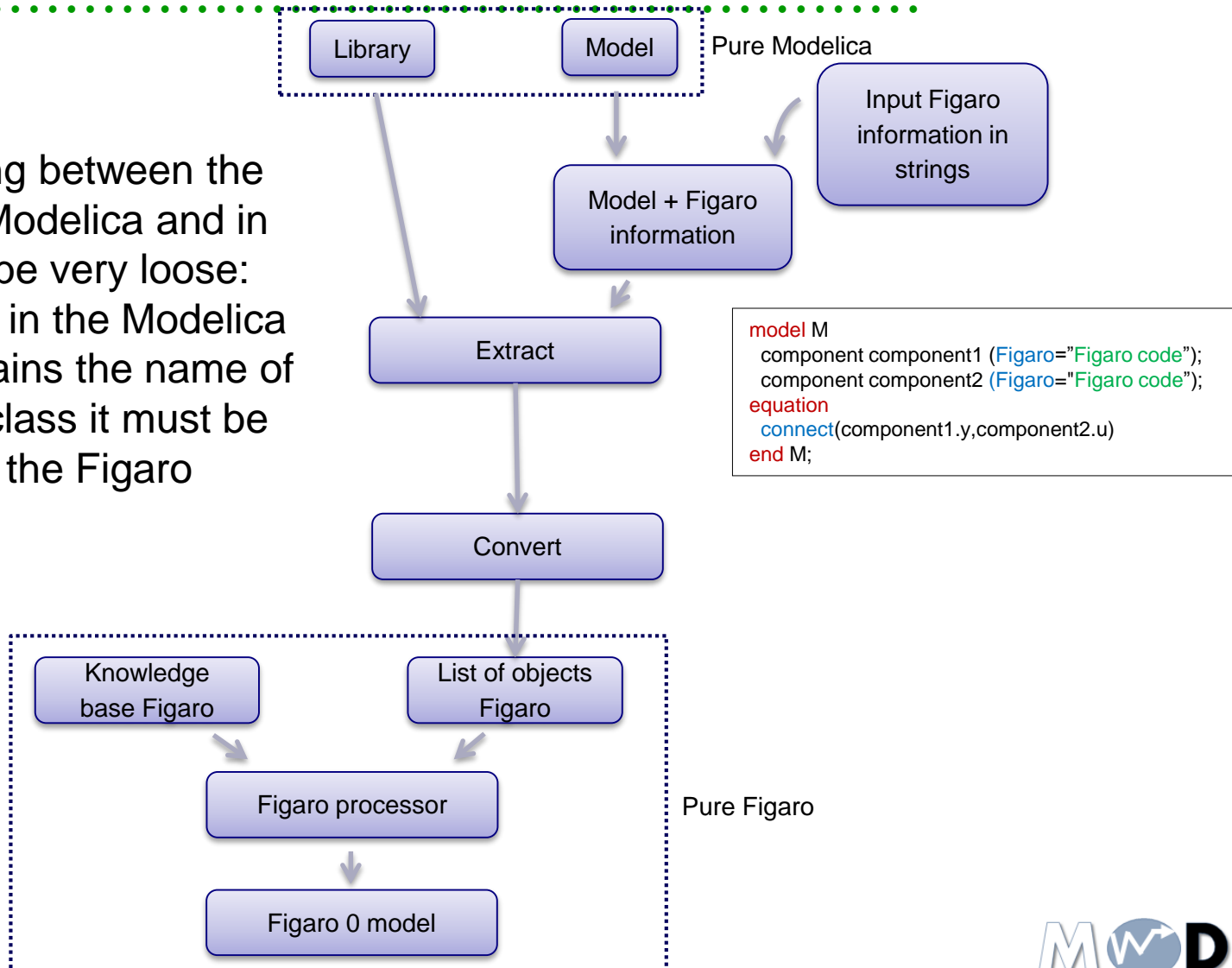


# The Modelica tools and KB3 work in similar ways



# Using Modelica in conjunction with the Figaro tools (the binding principle)

The mapping between the classes in Modelica and in Figaro can be very loose: each object in the Modelica model contains the name of the Figaro class it must be linked to by the Figaro processor



# Advantages of using the Figaro language and processor

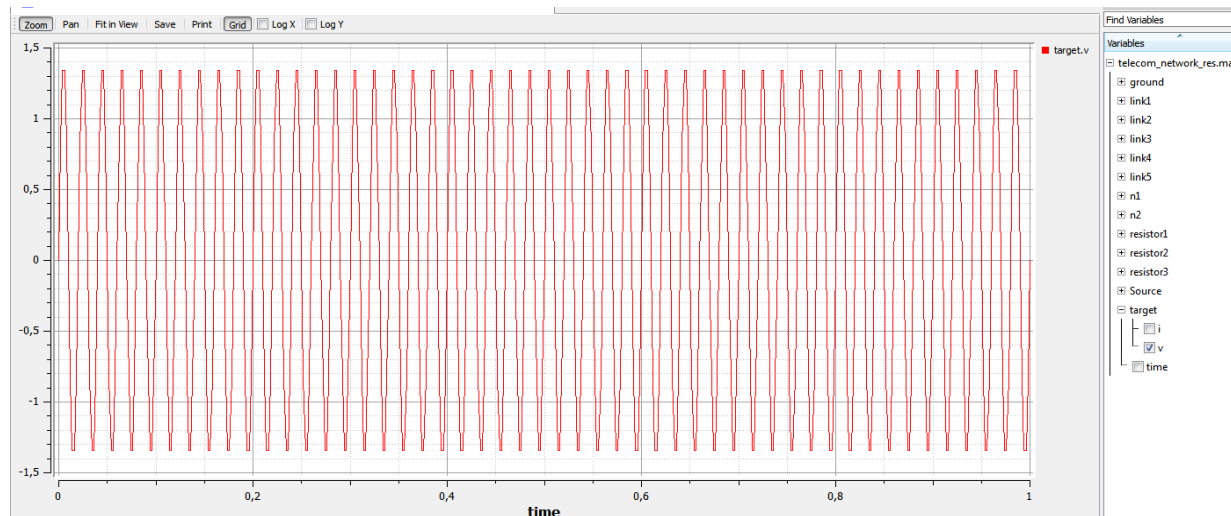
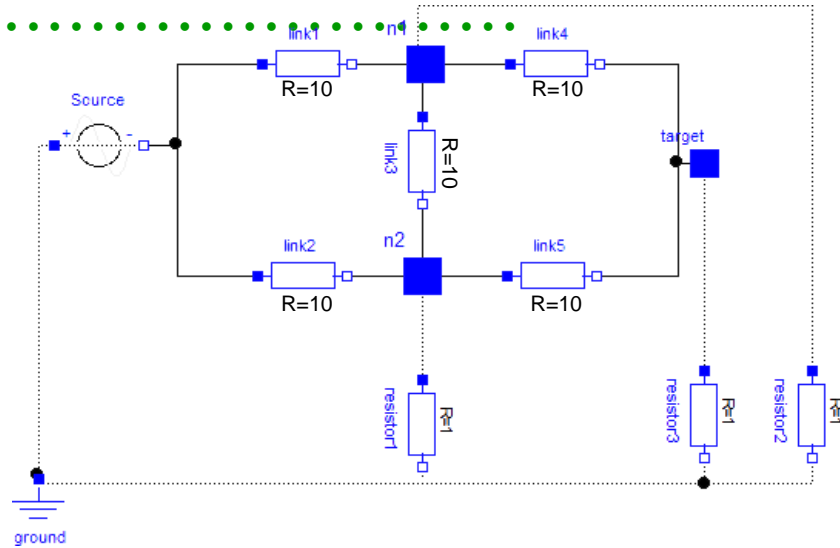
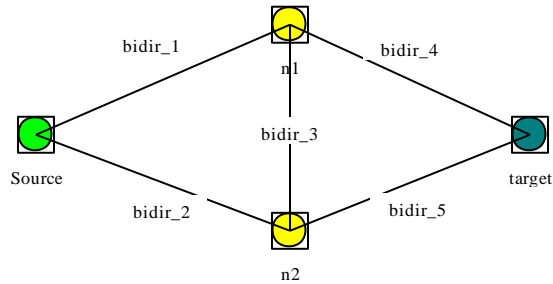
---

- Figaro: the first domain specific language for reliability (1990)
- Basis of the KB3 workbench: the reference tool at EDF
- Generic KB thanks to quantifiers
- Two ways to build FT
  - The CAT algorithm (Salem 1976) like most nowadays tools
  - **With macro components** => legible and structured FT
- Options to process negations (non coherent FT)
- Ability to produce correct FT for looped systems (cf. telecom example)

S. Salem, G.E. Apostolakis, D. Okrent : "A computer oriented approach to fault tree construction" EPRI-NP-288. 1976

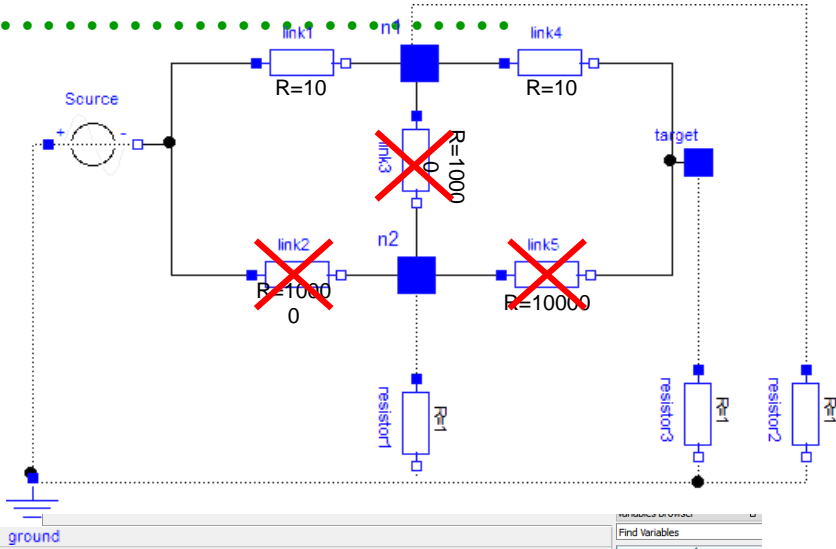
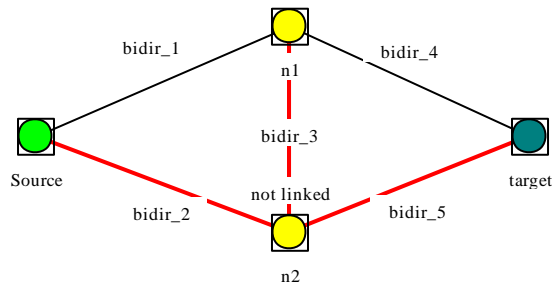
# Example: telecom network

## Nominal mode



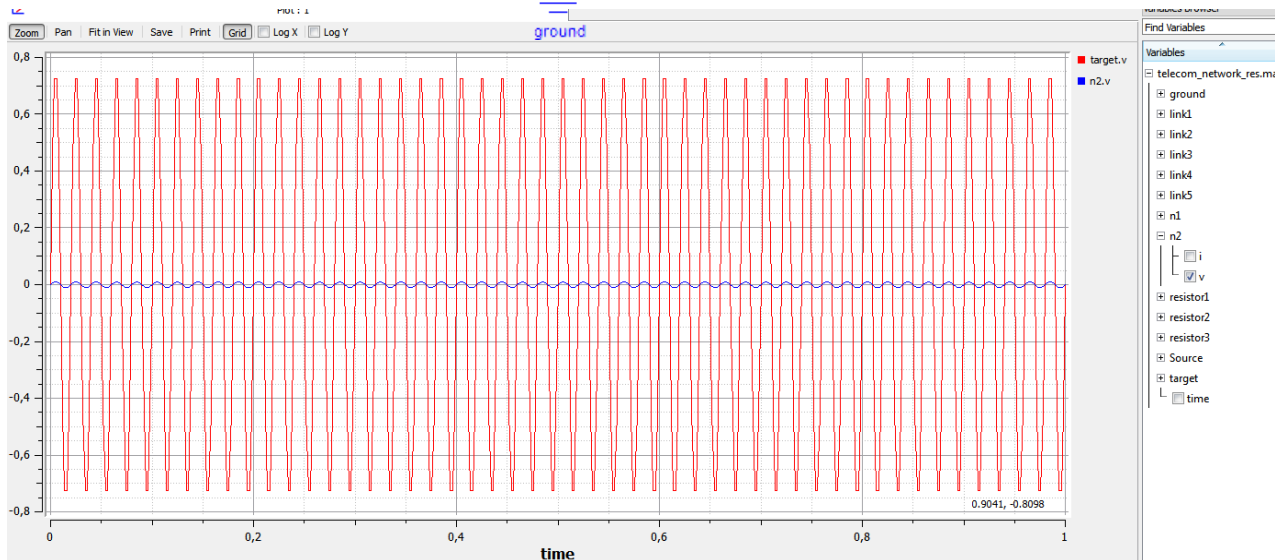
# Example: telecom network

## Degraded mode



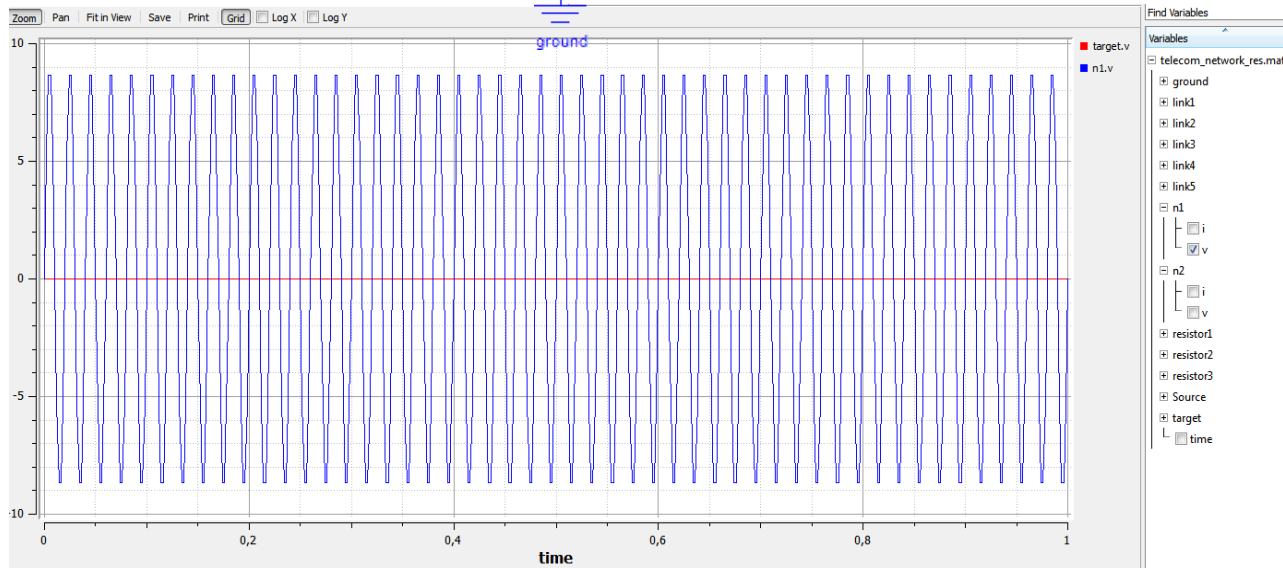
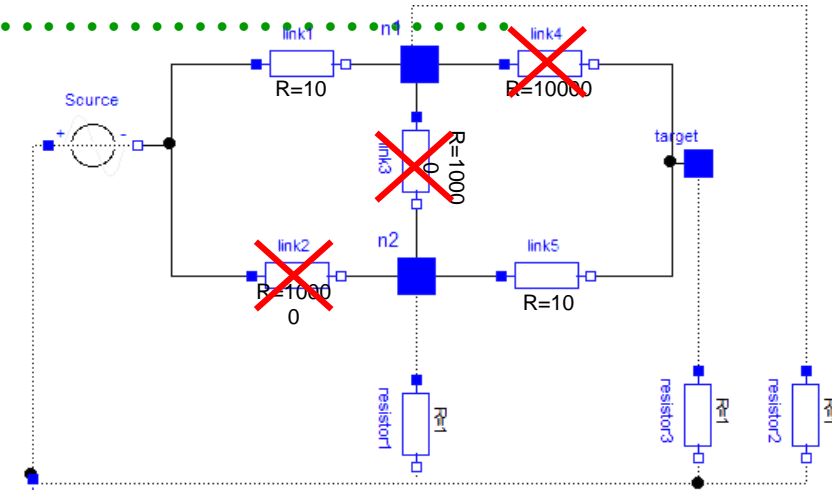
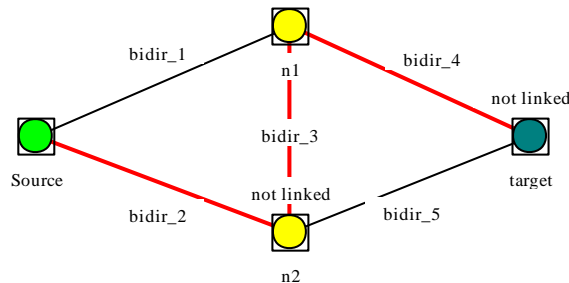
target.v

n2.v



# Example: telecom network

## Failure of the mission



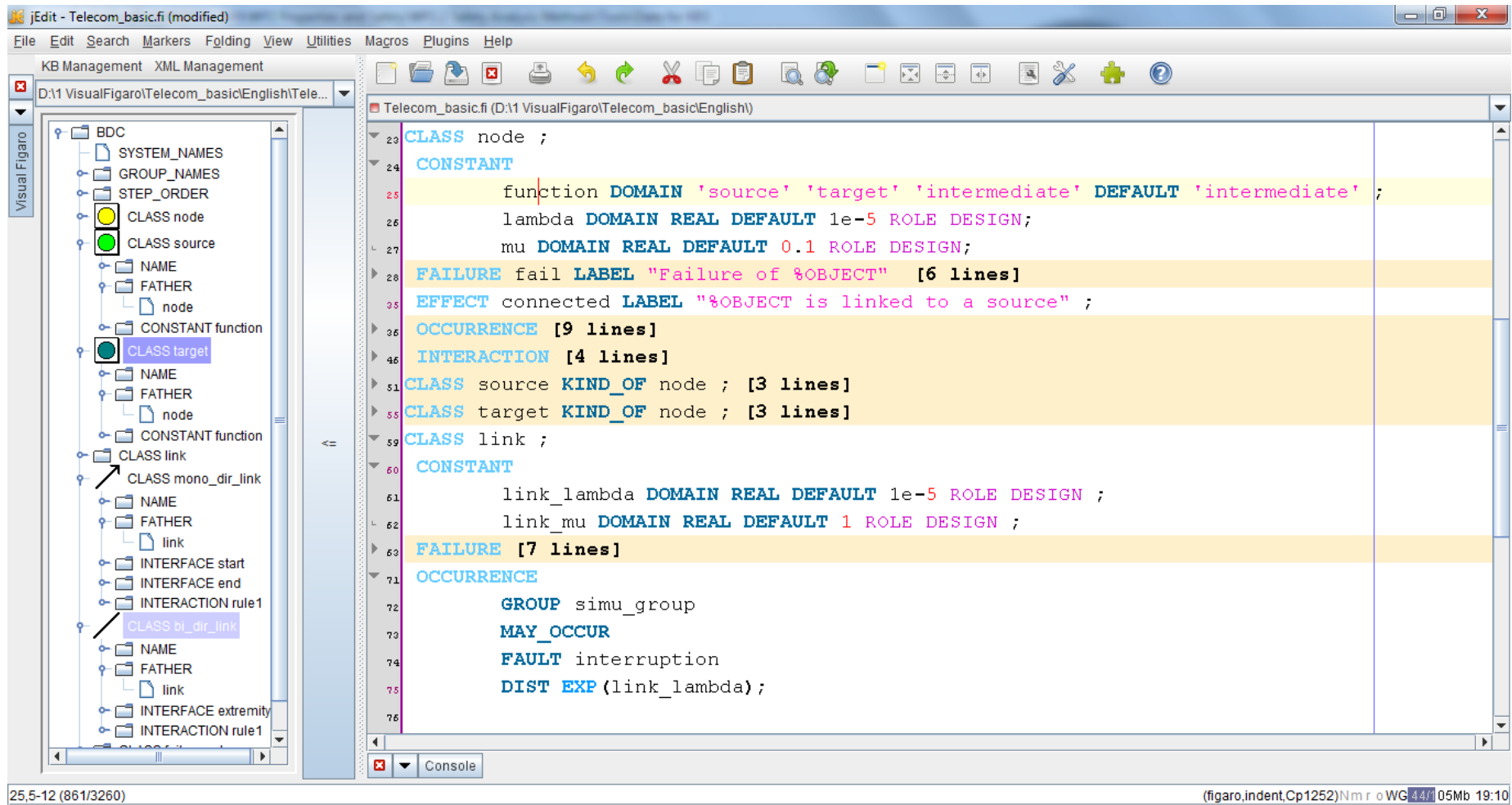
n1.v

target.v

We want to get the **exhaustive** list of minimal cut sets, **without** trying all combinations of failures in Modelica!

# Telecom network: the FIGARO library

Presentation at DCDS 2015



The screenshot displays the Visual Figaro editor interface. On the left, a tree view shows the library structure under 'BDC', including folders for 'SYSTEM\_NAMES', 'GROUP\_NAMES', 'STEP\_ORDER', and several 'CLASS' entries like 'node', 'source', 'target', 'link', 'mono\_dir\_link', and 'bi\_dir\_link'. The main editor window shows the source code for 'Telecom\_basic.fi' with the following content:

```

23 CLASS node ;
24 CONSTANT
25     function DOMAIN 'source' 'target' 'intermediate' DEFAULT 'intermediate' ;
26     lambda DOMAIN REAL DEFAULT 1e-5 ROLE DESIGN;
27     mu DOMAIN REAL DEFAULT 0.1 ROLE DESIGN;
28 FAILURE fail LABEL "Failure of %OBJECT" [6 lines]
35 EFFECT connected LABEL "%OBJECT is linked to a source" ;
36 OCCURRENCE [9 lines]
37 INTERACTION [4 lines]
46 CLASS source KIND_OF node ; [3 lines]
55 CLASS target KIND_OF node ; [3 lines]
59 CLASS link ;
60 CONSTANT
61     link_lambda DOMAIN REAL DEFAULT 1e-5 ROLE DESIGN ;
62     link_mu DOMAIN REAL DEFAULT 1 ROLE DESIGN ;
63 FAILURE [7 lines]
71 OCCURRENCE
72     GROUP simu_group
73     MAY_OCCUR
74     FAULT interruption
75     DIST EXP (link_lambda);
76

```

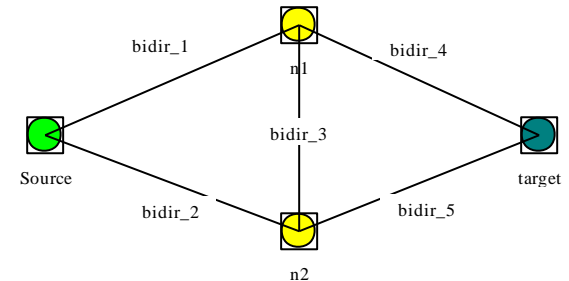
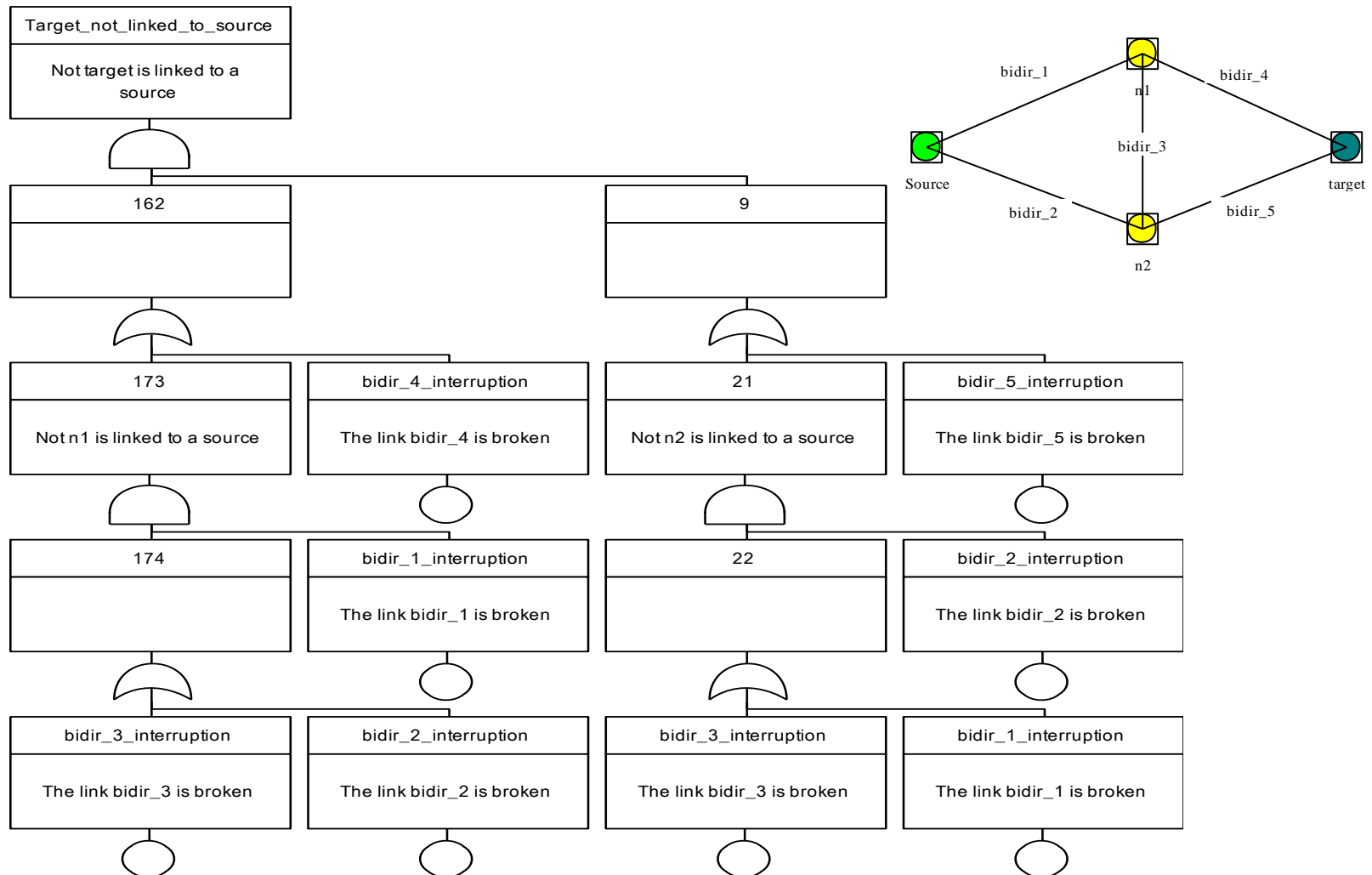
At the bottom of the editor, a console window is visible. The status bar at the bottom of the application shows '25,5-12 (861/3260)' on the left and '(figaro.indent,Cp1252)Nm r oWG 44 05Mb 19:10' on the right.

The library is edited in the Visual Figaro editor  
Total length: 115 lines



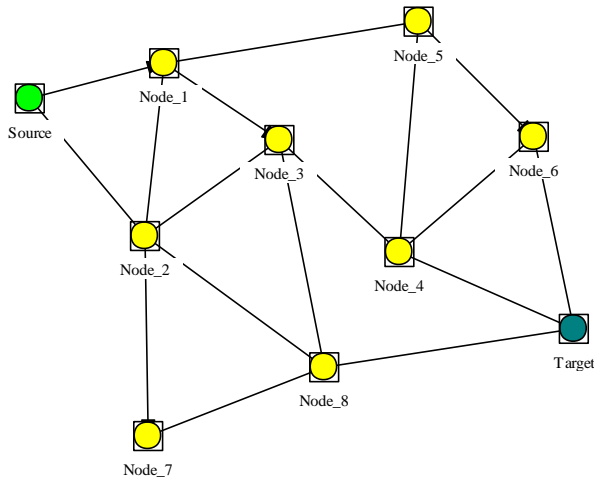
# Example: telecom network

## Fault tree generated by the FIGARO processor

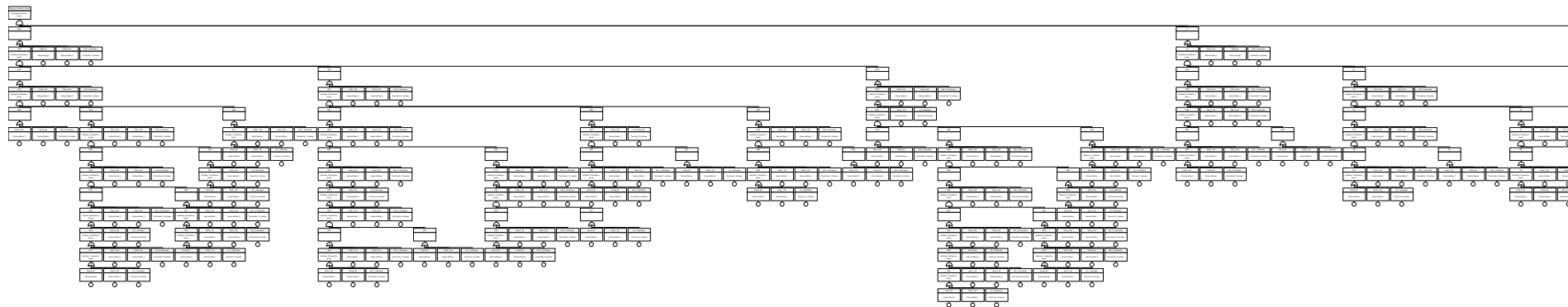


(considering nodes as perfect to get a small fault tree)

# It could also work for a more complicated case...



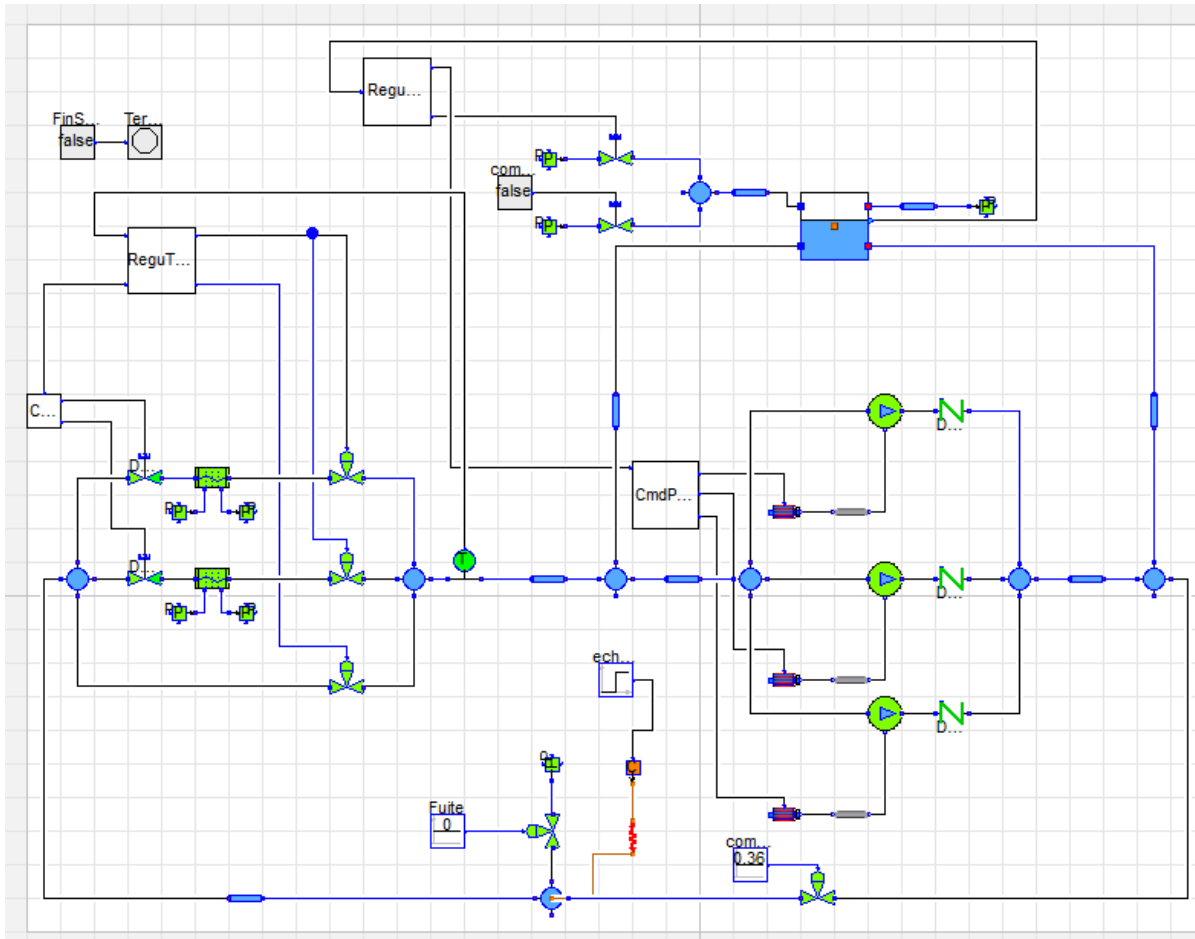
Generation of a fault tree eliminating loops by KB3 (failures of nodes **and** links taken into account)



First third of the fault tree...

# Example 2: thermohydraulic system (SRI)

- Real use case of MODRIO
- Cooling system in a nuclear power plant

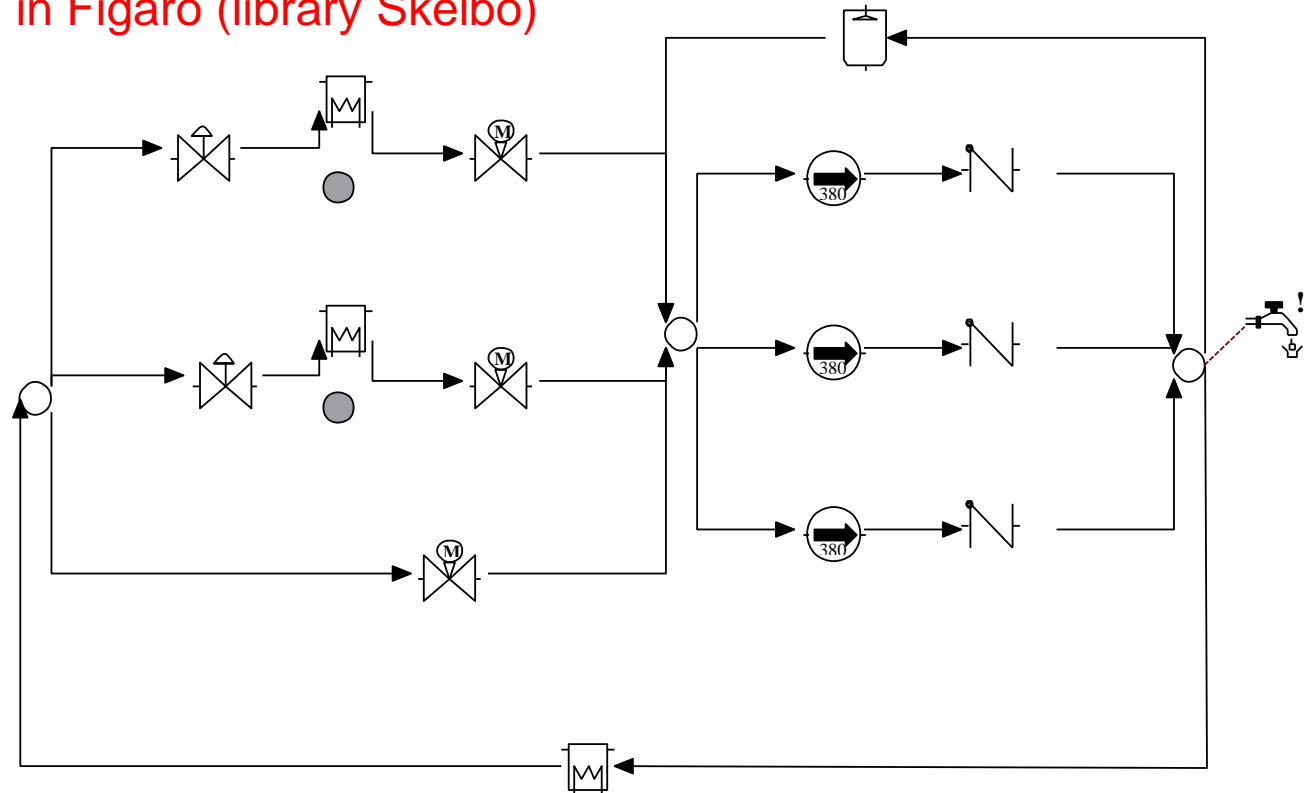


SRI in Modelica  
(library ThermosysPro)

# The SRI as it would be input in KB3

- The Figaro library (Skelbo) was developed long ago, independently from the SRI model in Modelica

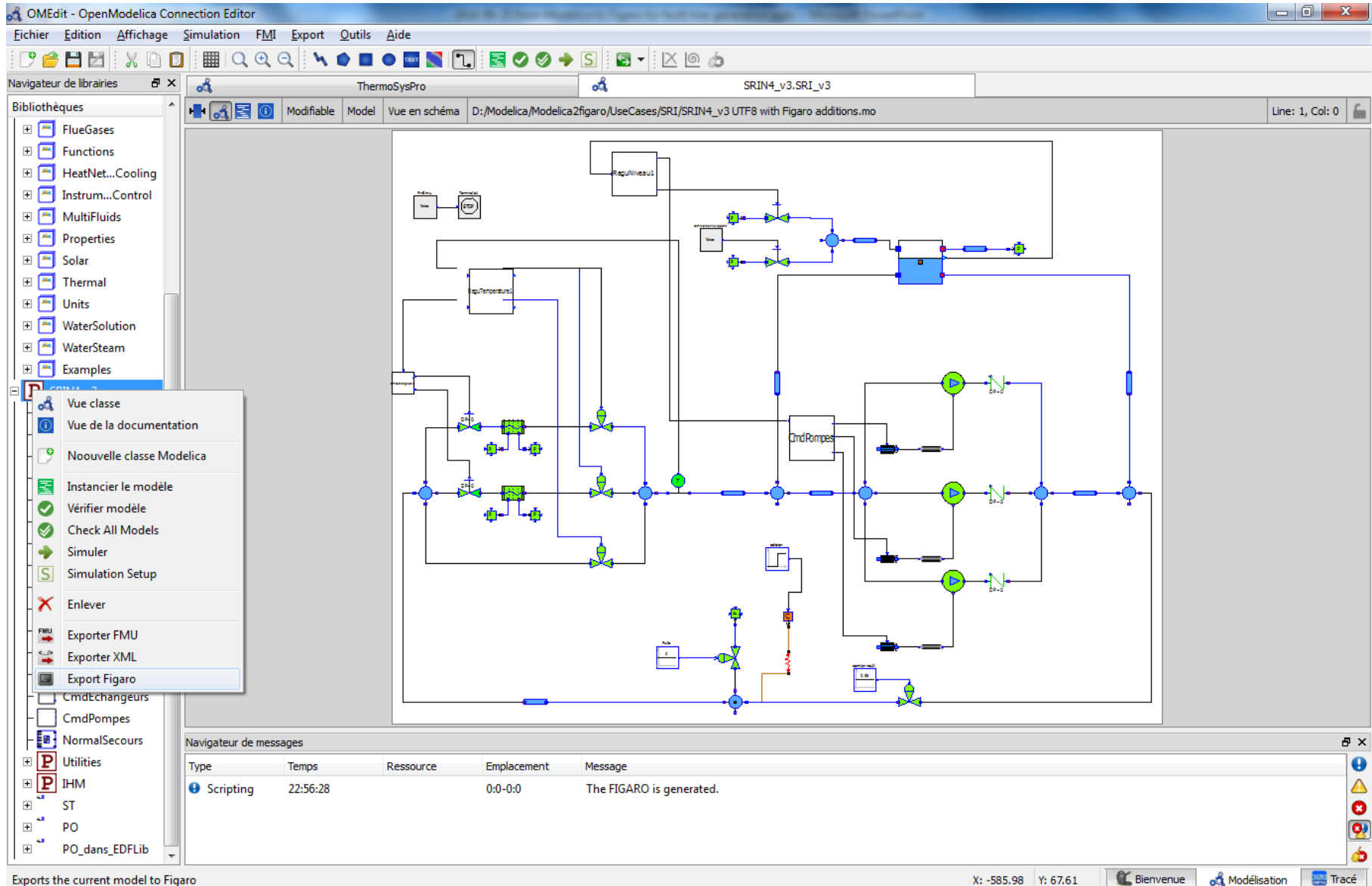
SRI in Figaro (library Skelbo)



In fact, the same topological information is input in the Modelica model

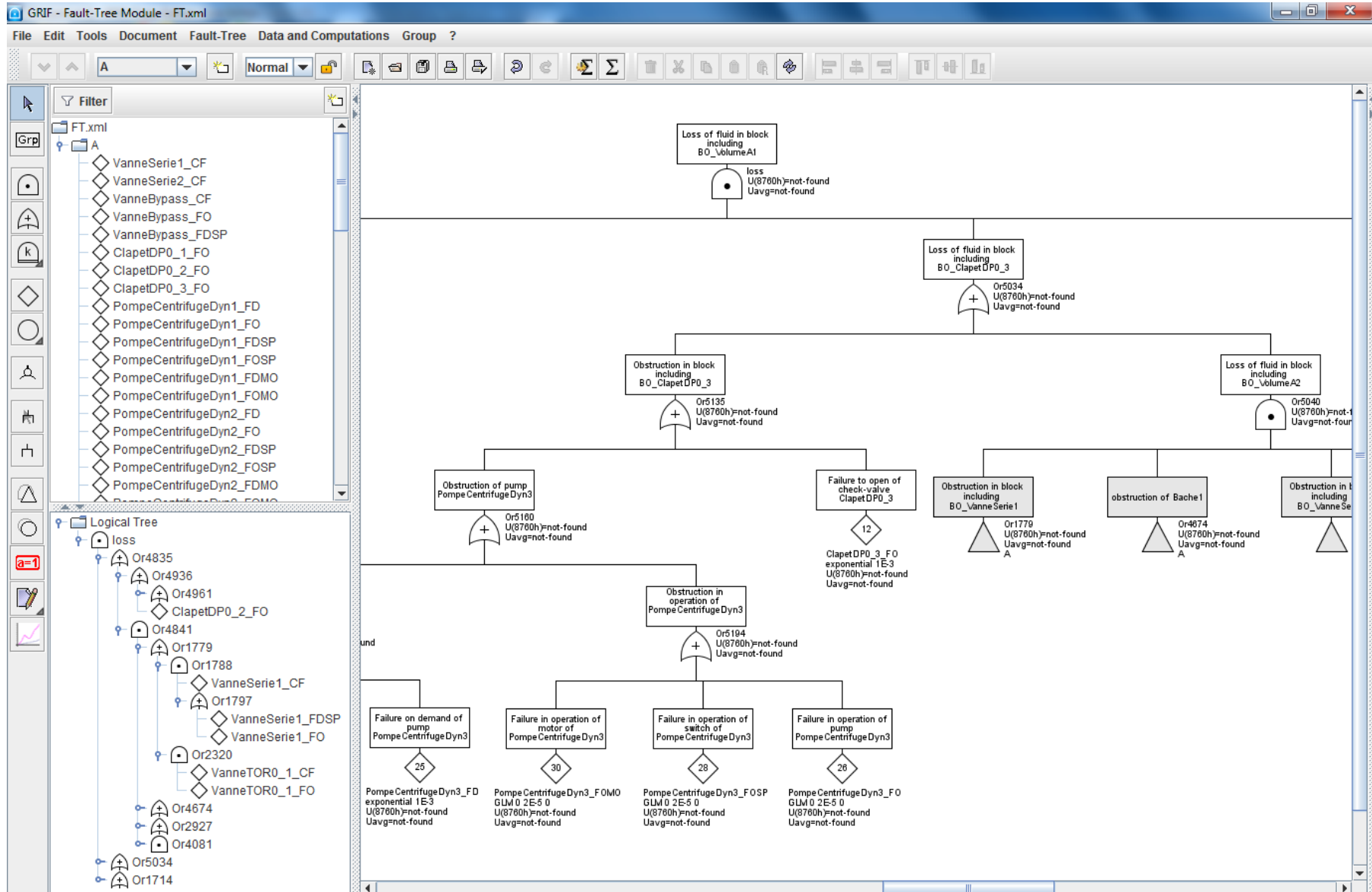
# Demonstration: OpenModelica

Presentation at DCDS 2015

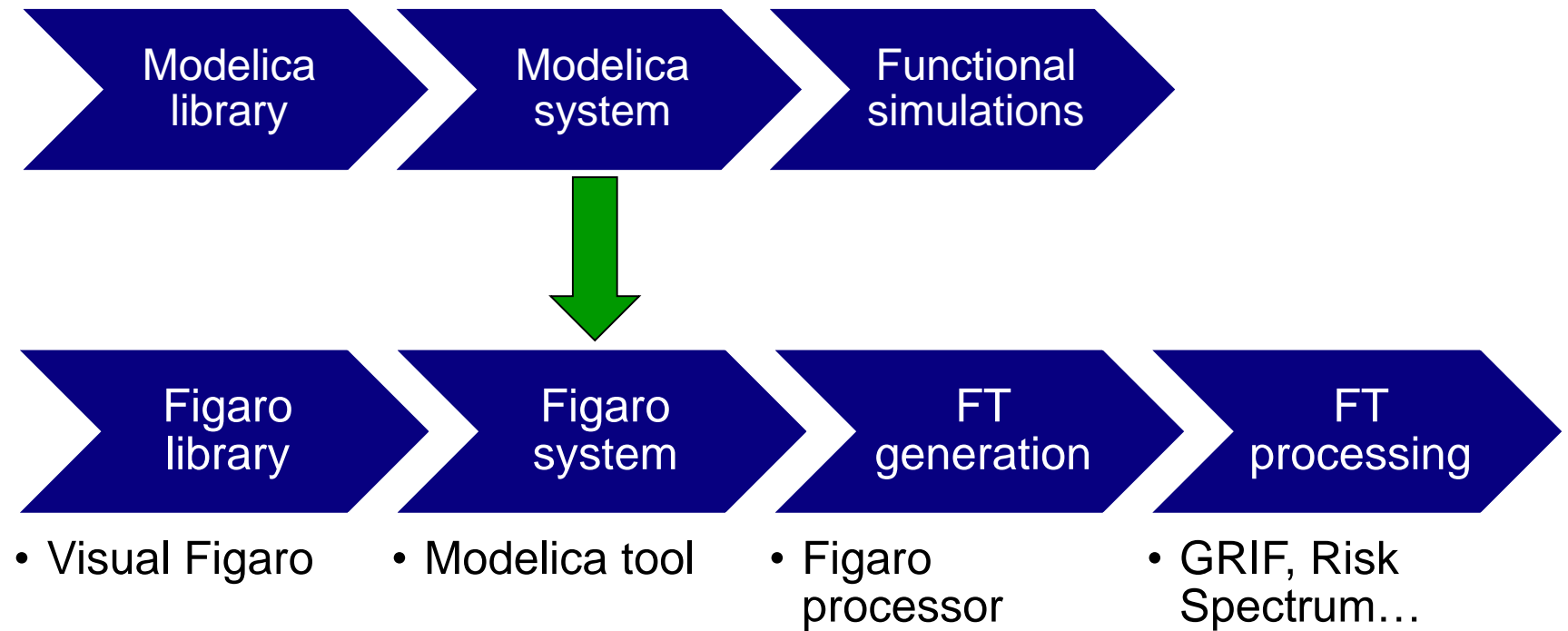


The screenshot displays the OpenModelica Connection Editor (OMEdit) interface. The main window shows a complex piping diagram with various components like pumps, valves, and heat exchangers. A context menu is open over the diagram, listing various actions such as 'Vue classe', 'Noouvelle classe Modelica', 'Instancier le modèle', 'Vérifier modèle', 'Simuler', and 'Export Figaro'. The 'Export Figaro' option is highlighted. The interface includes a menu bar (Fichier, Edition, Affichage, Simulation, FMI, Export, Outils, Aide), a toolbar, and a message navigator at the bottom showing a successful 'Scripting' message: 'The FIGARO is generated.' The status bar at the bottom indicates the current coordinates (X: -585.98, Y: 67.61) and the current state (Bienvenue, Modélisation, Tracé).

# The generated fault tree in the GRIF editor



# Summary: engineering workflow



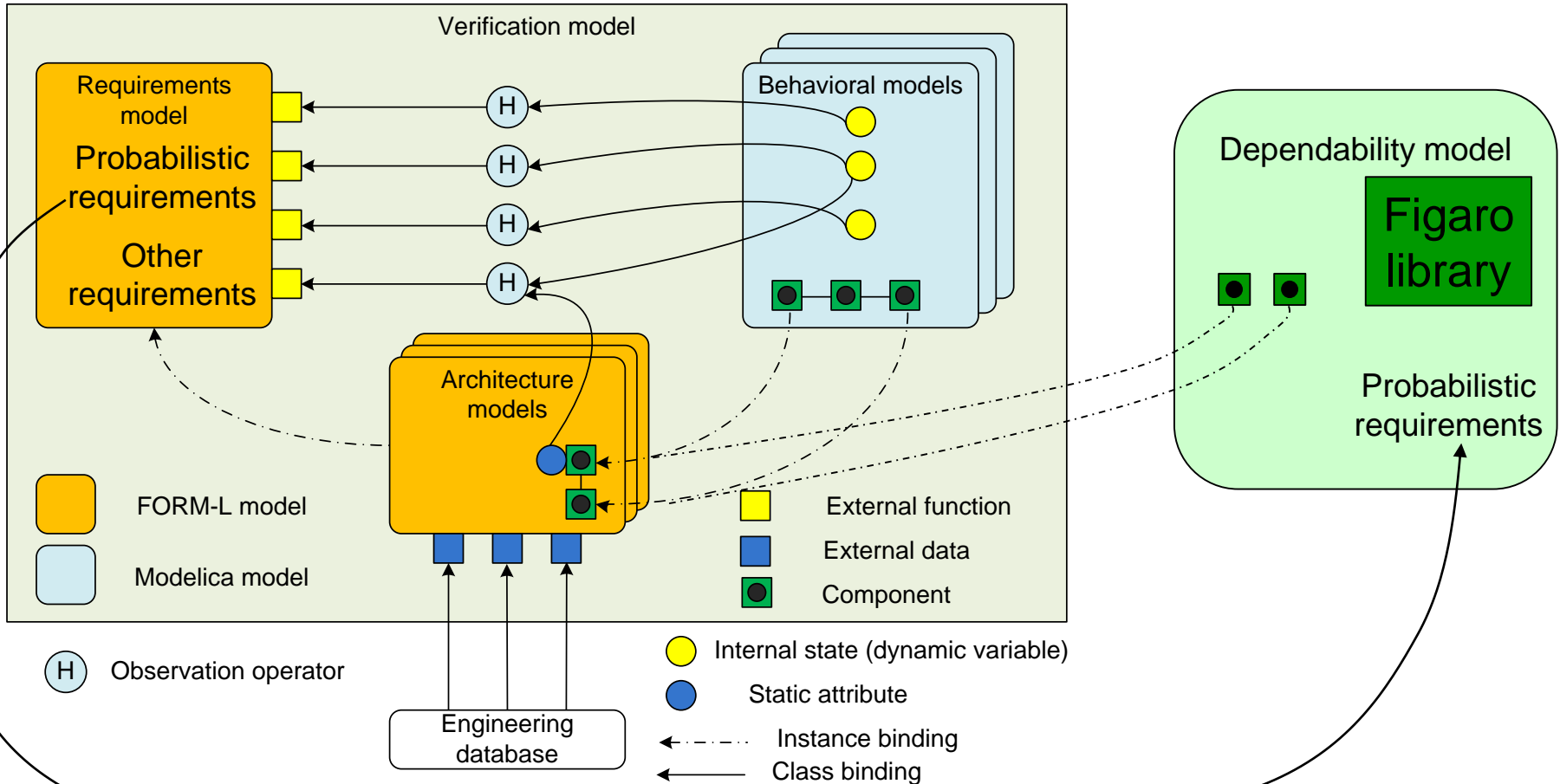
## Conclusion of Part 2

---

- Main advantage of this approach: relies on mature tools and formalisms
- Smart fault tree generator
  - Can use automatically generated macro components
  - Handles looped systems properly
- No need to change the Modelica model, nor the Figaro library
- The Figaro and Modelica parts are loosely coupled: no need to have a bijection between the elements of the two models
- It will be possible to propose an enhanced GUI to help the user input correct Figaro additions (with pull down menus...)



# Perspective: binding the Figaro model to Form-L models



.....

## THANK YOU!

Where to find more information on tools:

<http://openmodelica.org> download OpenModelica with Figaro text-only tools

<http://sourceforge.net/projects/visualfigaro/> download KB3 and other Figaro based tools

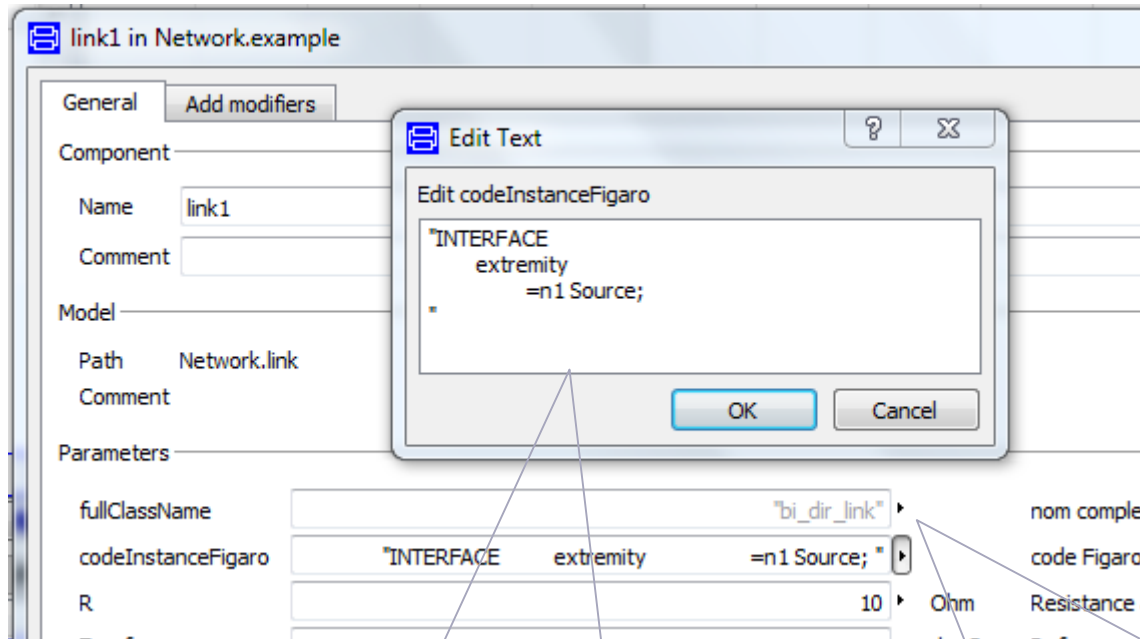
<http://marc.bouissou.free.fr/> papers on the principles of Figaro tools

<http://rdsoft.edf.fr> then link to KB3: general information on KB3



# COMPLEMENTS

# Telecom network: the FIGARO information that must be added in the Modelica model



The screenshot shows the Modelica IDE interface for editing a component named 'link1'. An 'Edit Text' dialog box is open, displaying the FIGARO code: `"INTERFACE extremity =n1 Source;".` The background editor shows the 'codeInstanceFigaro' field with the same code and the 'fullClassName' field with the value 'bi\_dir\_link'.

In the Modelica model, the class "link" is a subclass of:

- The electrical component resistor
- The generic class FIGARO that contains only two string parameters A and B

A: The only Figaro code the user has to input (for every link)

B: The name of the corresponding class in the FIGARO library is defined in the class "link"

# Limitations of the CAT algorithm

## 3. CRITICISM OF THE CAT ALGORITHM

Let us consider a simple but useful example for the following discussions. Let us analyze a circuit composed of a series of three resistors (Fig. 2)

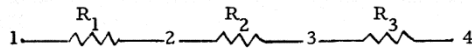


Figure 2

In particular we will analyze those failures causing the current loss at point 3. CAT models as presented in [1] will be used. Since this problem is essentially related to the existence of a signal in a particular point of the circuit, the choice will be of "current type".

Therefore, as the current flows from node 1 to node 4, the  $i$ -th resistor simplified model will be as follows:

$$\begin{array}{ccc} I_i & SR_i & I_{i+1} \\ 0 & - & 0 \\ - & 1 & 0 \\ 1 & - & 1 \end{array}$$

where - = don't care state

$I_i$  = current at  $i$ -th node (0 = no current)

$SR_i$  = state of  $i$ -th resistor

$SR_i = \begin{cases} 0 & \text{resistor good} \\ 1 & \text{resistor failed} \end{cases}$

With orientation from left to right, in the generated FT for  $I_3=0$ ,  $R_3$  does not appear

With the macro component approach of KB3, the model states:

- failure of  $R_i \Rightarrow$  failure of MC
- failure of MC  $\Rightarrow I_i = 0$

G. Squellati "Critical review of the CAT algorithms for automated fault tree construction". JRC technical note N° 1.06.01.80.84. **October 1980**