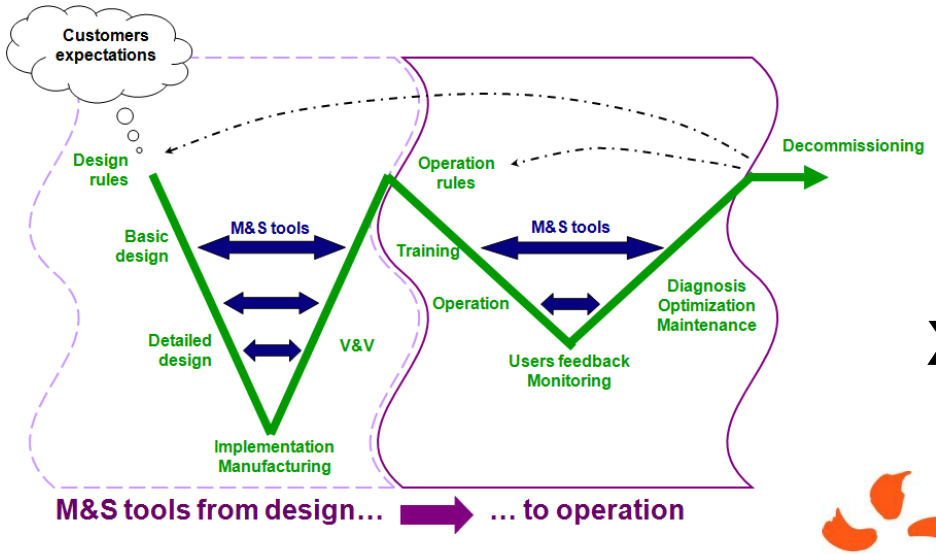
ITEA 2

INFORMATION TECHNOLOGY FOR EUROPEAN ADVANCEMENT



From Modelica models to dependability analysis

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LMCS 2015

MODRIO

Industrial challenge

- Separation of design and dependability analysis workflows
- Consequences:
  - The same information is input twice
  - Consistence is not guaranteed
  - Long delay between the two kinds of studies => no possibility of feedback, except for very serious issues

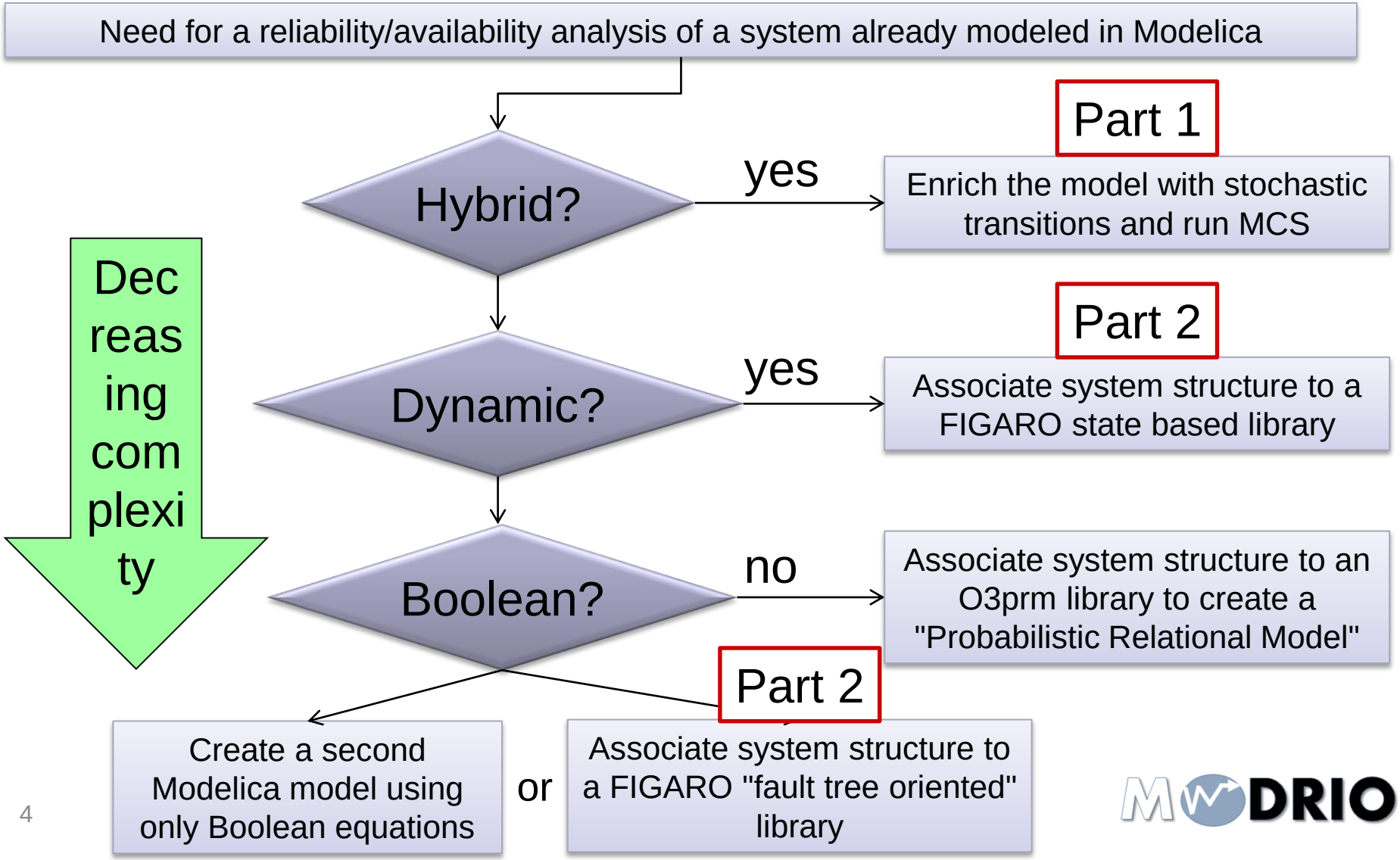
- Existing attempts to link design models to dependability:
  - Limited to fault tree production (+ FMEA)
  - Rely on a simple algorithm (assembly of FT parts, not a true *generation*), works for control systems but not for physical systems
  - No storage of *generic* reliability models

Modelica and Figaro: two DSLs

- Modelica: system design and functional validation
  - Deterministic physical models: algebraic and differential equations (DAE)
  - Object oriented
  - Declarative and procedural parts
  - Supported by a large number of tools (open source or commercial)

- Figaro: system dependability analysis
  - Discrete stochastic models: states and stochastic transitions
  - Object oriented
  - Declarative (based on occurrence and interaction rules)
  - Supported by the KB3 platform (partly free. Should be open source soon)

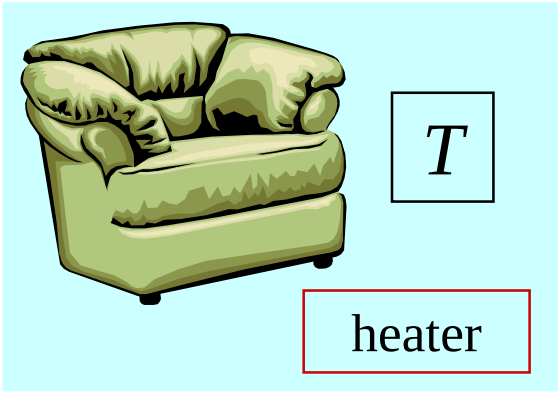
Various ways to derive stochastic models from Modelica models



Outline of part 1

- Introduction of stochastic transitions in Modelica
  - A simple test case
  - Modeling it using state machines
- Two more complex examples
- Perspectives

The "Heated room" test case

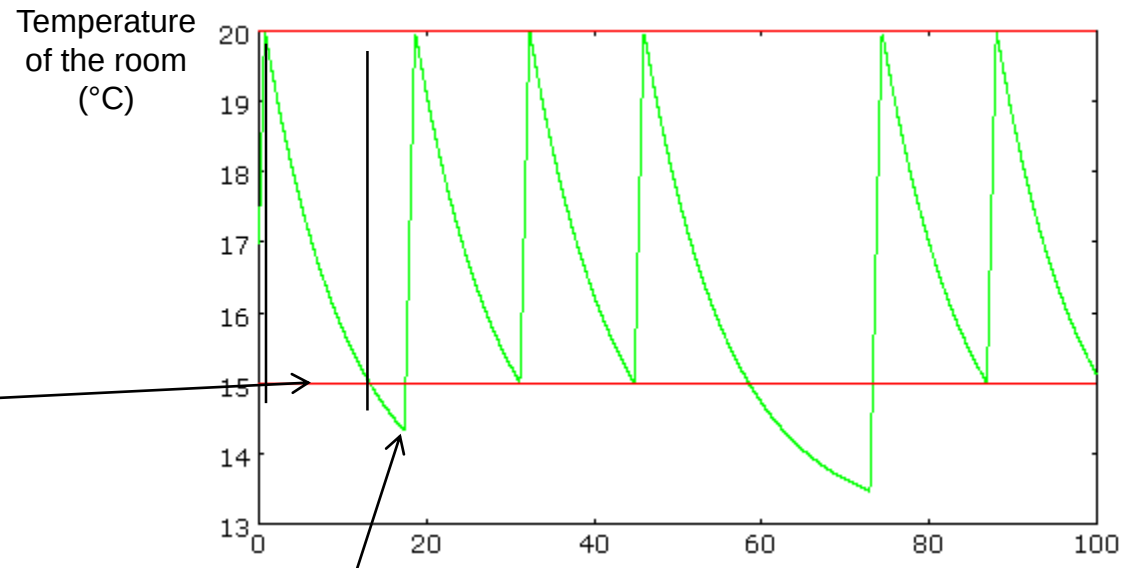


T_E External temperature

Heater:

- on at Tmin, off at Tmax
- subject to random failures and repairs
- exponential distributions for times to failure and times to repair

An example of single (random) trajectory of T

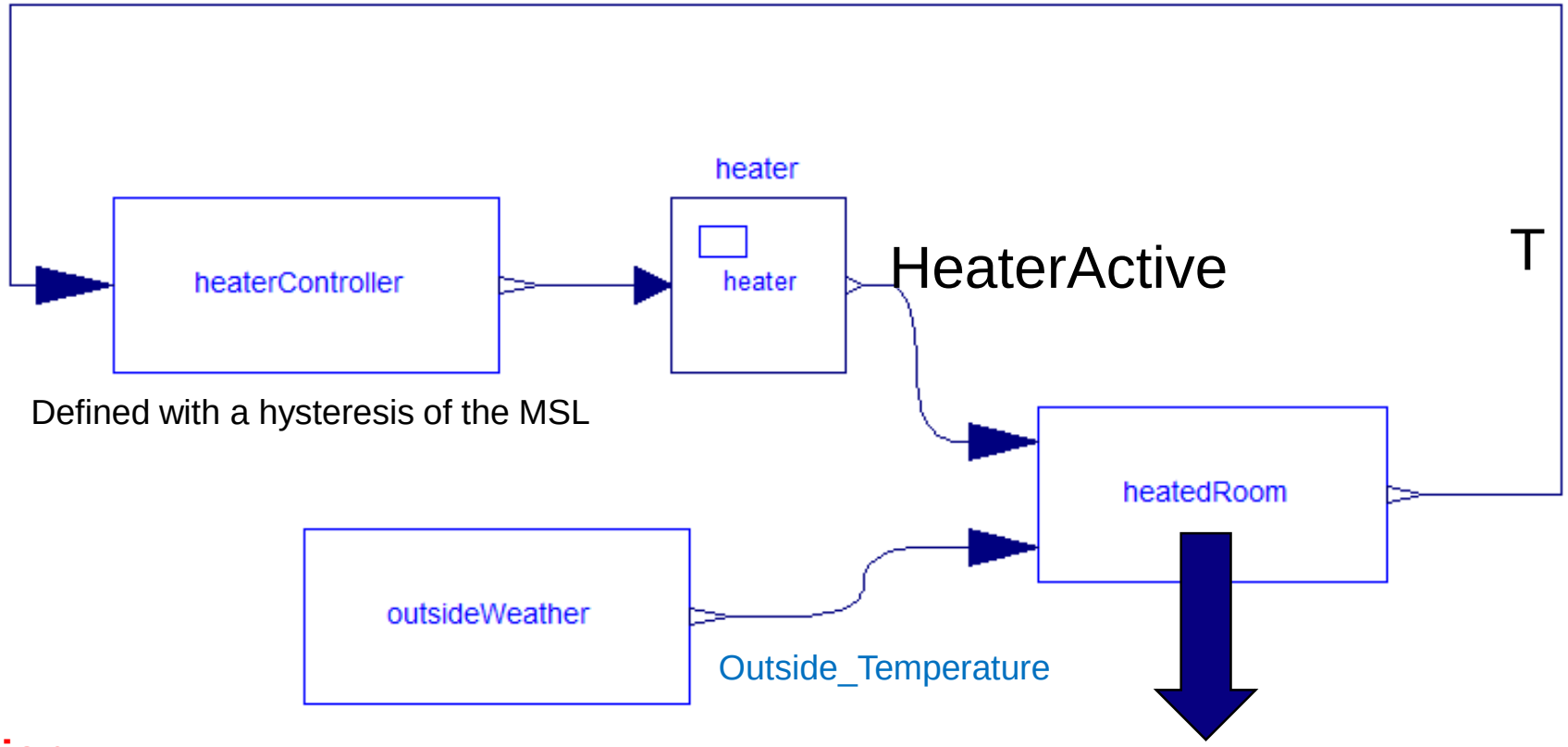


A failure of the heater occurred somewhere here

And was repaired at that time

This is a PDMP:
Piecewise Deterministic Markov Process

Modelica model: structure



equation

der(T)= CoeffHeaterController*HeaterActive +
CoeffOutsideTemperature*(Outside_Temperature - T) ;

The heater: a first model

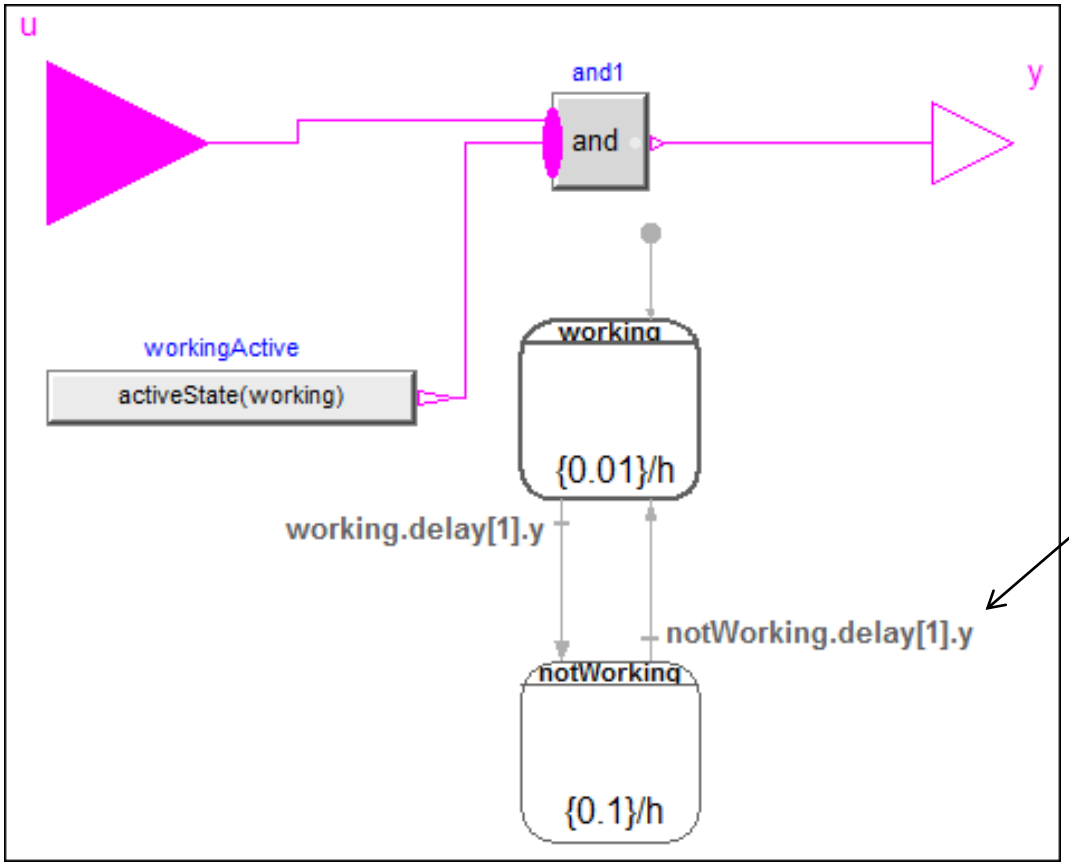
```
algorithm
when initial() then
  F := seed; //each calculation of F will yield a pseudo random number
in [0,1]
end when;
// Attention: the two following rules must not be merged in a single one!
when initial() then    //calculating the first random working time
    F := mod(a*F+c, m);
    x := F / m;
    X:= (-log(1-x))/lambda;
end when;
when  working then //random draw of the next working time
    F := mod(a*F+c, m);
    x := F / m;
    X:= (-log(1-x))/lambda;
end when;
// X is the working time
when working and (time - starttime_working) > X then
    working := false;
    starttime_notworking := time;
end when;
```

…. Similar instructions for repairs

```
// Input-output relation
equation
if working then
  y =  u;
 else
    y =  0.;
end if;
```

Very cumbersome and error prone!

The heater (in Modelica 3.3)



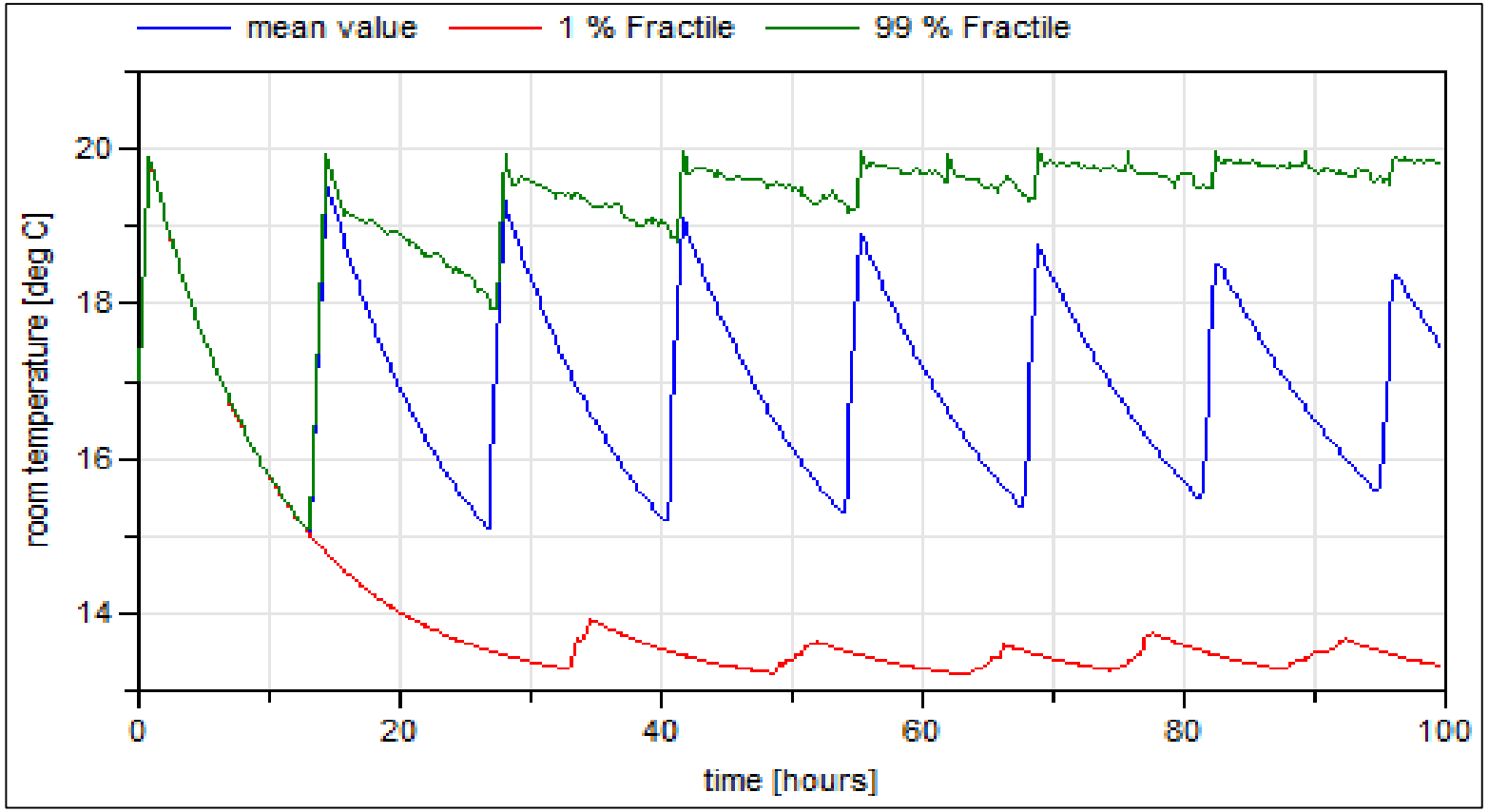
Essentially the same principles as what was shown on slide "Heater: a first model", but taking advantage of abstraction mechanisms provided by Modelica.

The user does not have to write any code

We use a continuous time state machine to describe the random behavior of the heater (only available in Dymola, cf. *Modelica extensions for multi-mode DAE systems*, Elmqvist, Mattsson and Otter, 2014)

Results: Temperature
(10000 random trajectories)

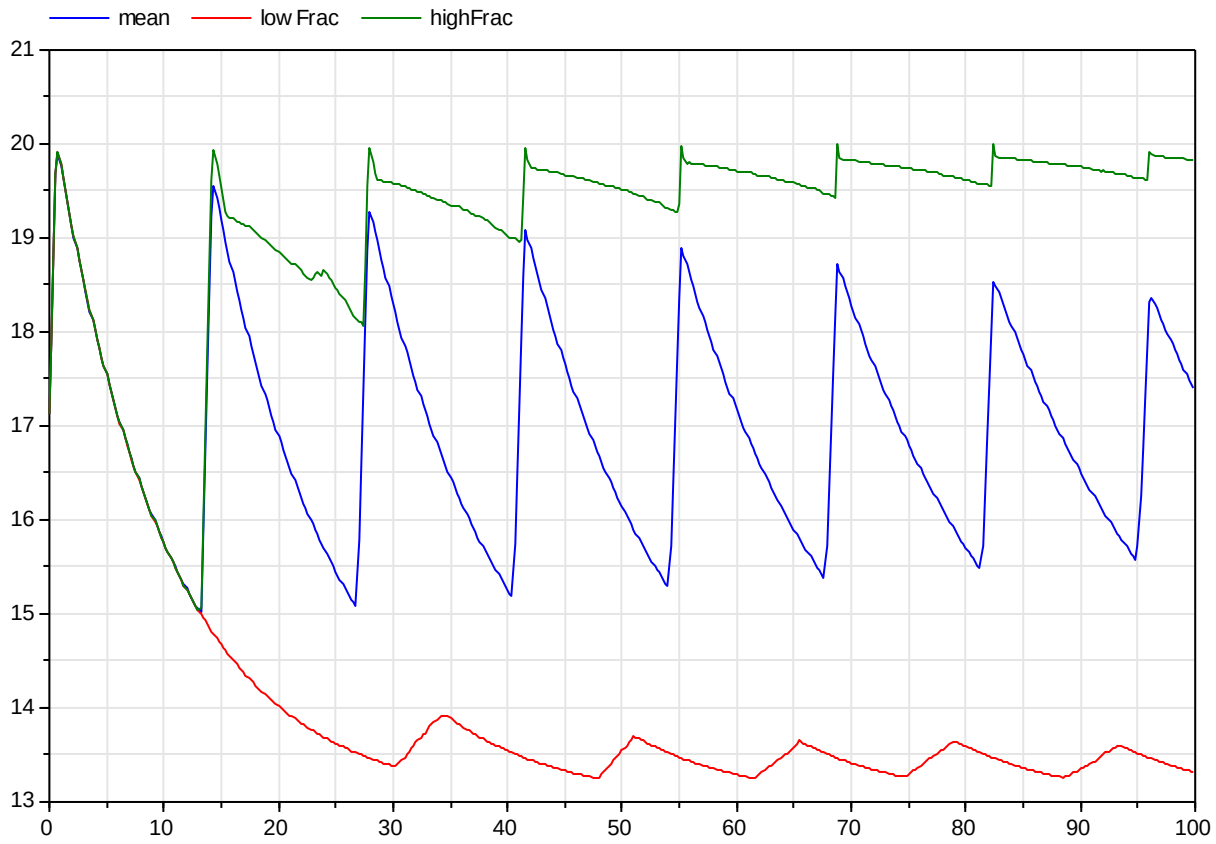
T(°C)



time (h)

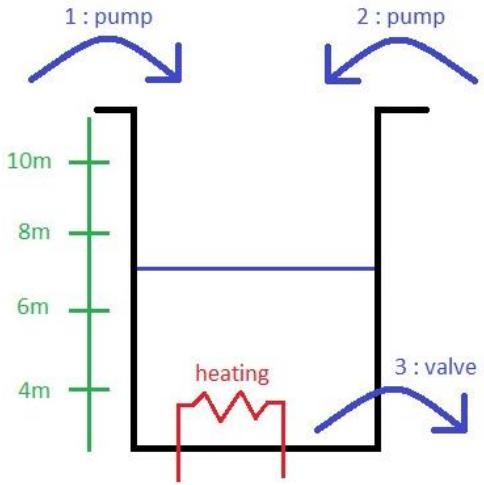
Results

- Heated-room
- 1 000 000 sim
- 1h30



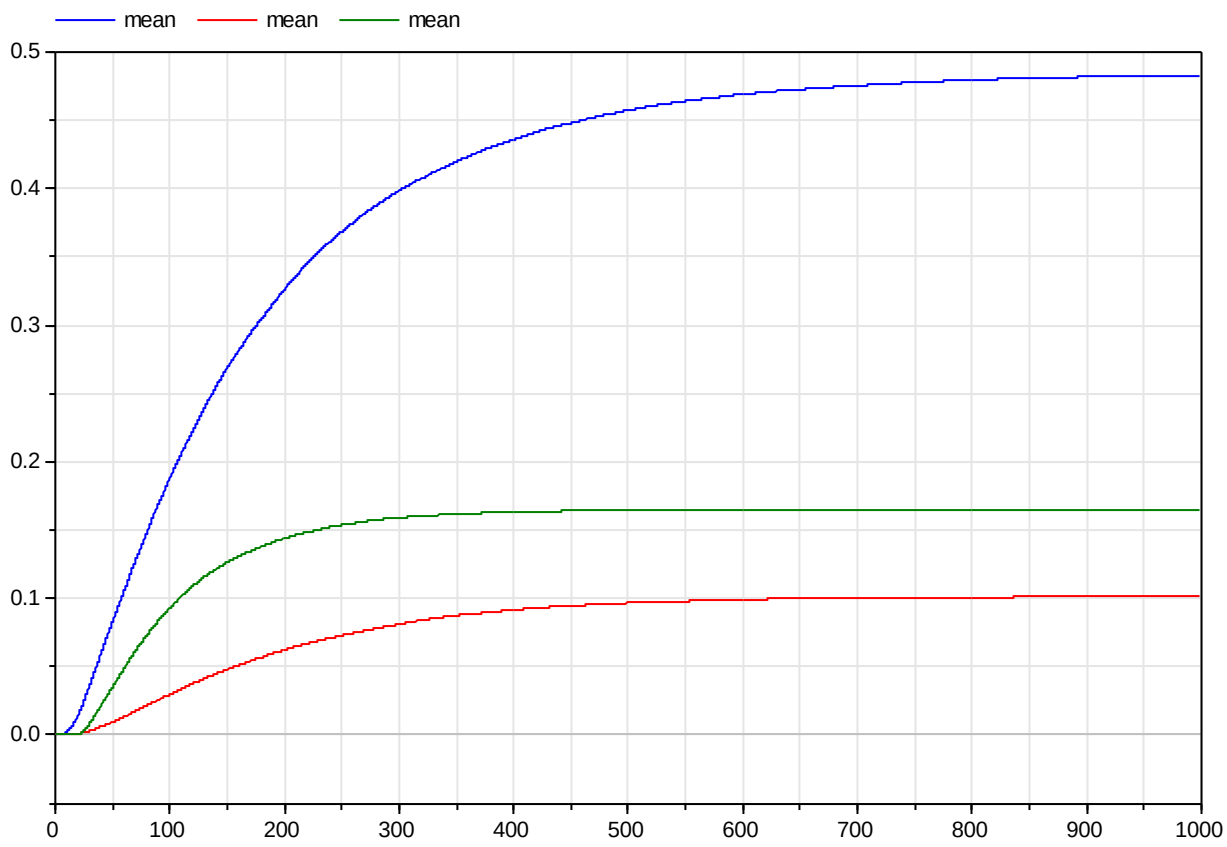
Ex 2 : heated-tank

- Tank with 2 pumps and 1 valve
- Failure rates dependent on temperature
- 2 tied continuous variables : temperature and level
- A test case solved with dozens of methods in the literature!



Results

- Heated-tank
- 100 000 sim
- 2h15
- Zhang et al. :
  1 min 30s
  or
  23h



Conclusion

- 3 complementary test cases were solved
- Random state machines work… in Dymola
- Monte Carlo works and is fairly efficient
- Anyway, faster than some other general* methods

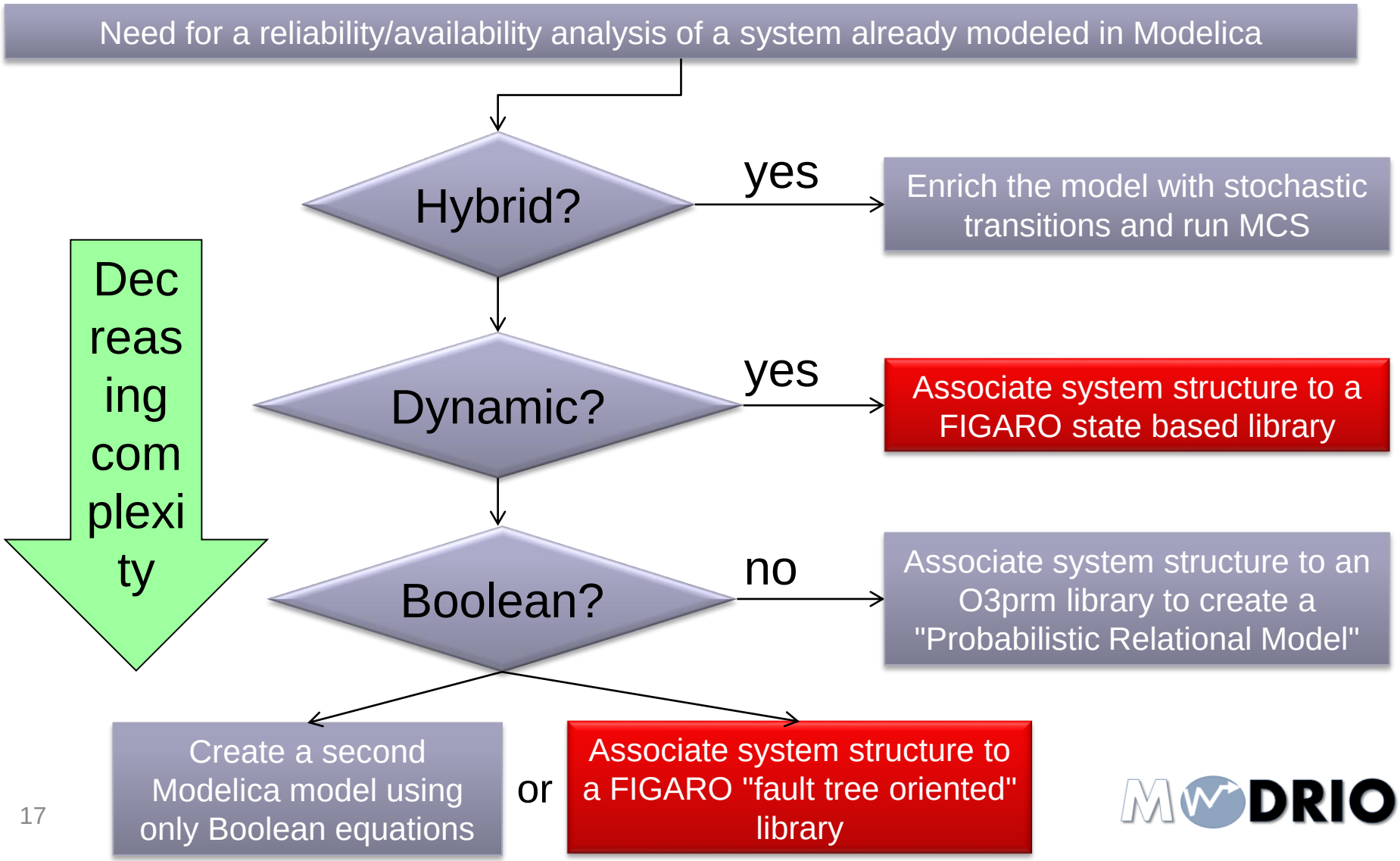
*General = that do not use analytical solutions for DAE

Perspectives

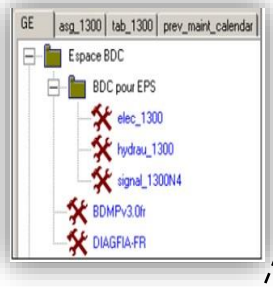
- Apply those principles to a complex system: a data center with electrical supplies, thermohydraulic cooling system
- Requires the extension of components models with stochastic state machines to represent failures, repairs, reconfigurations…
- Refine the Monte Carlo function

- Convince the Modelica association to introduce "native" stochastic transitions in Modelica!

Various ways to derive stochastic models from Modelica models



The Modelica tools and KB3 work in similar ways



Knowledge base

KB3

List of objects Figaro

Figaro 0 Model

Fault tree generation

Figseq

YAMS (MCS)

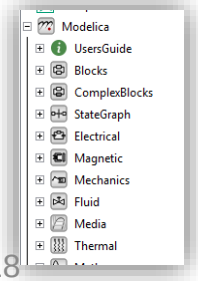
System

OpenModelica

Modelica System

Flat Modelica

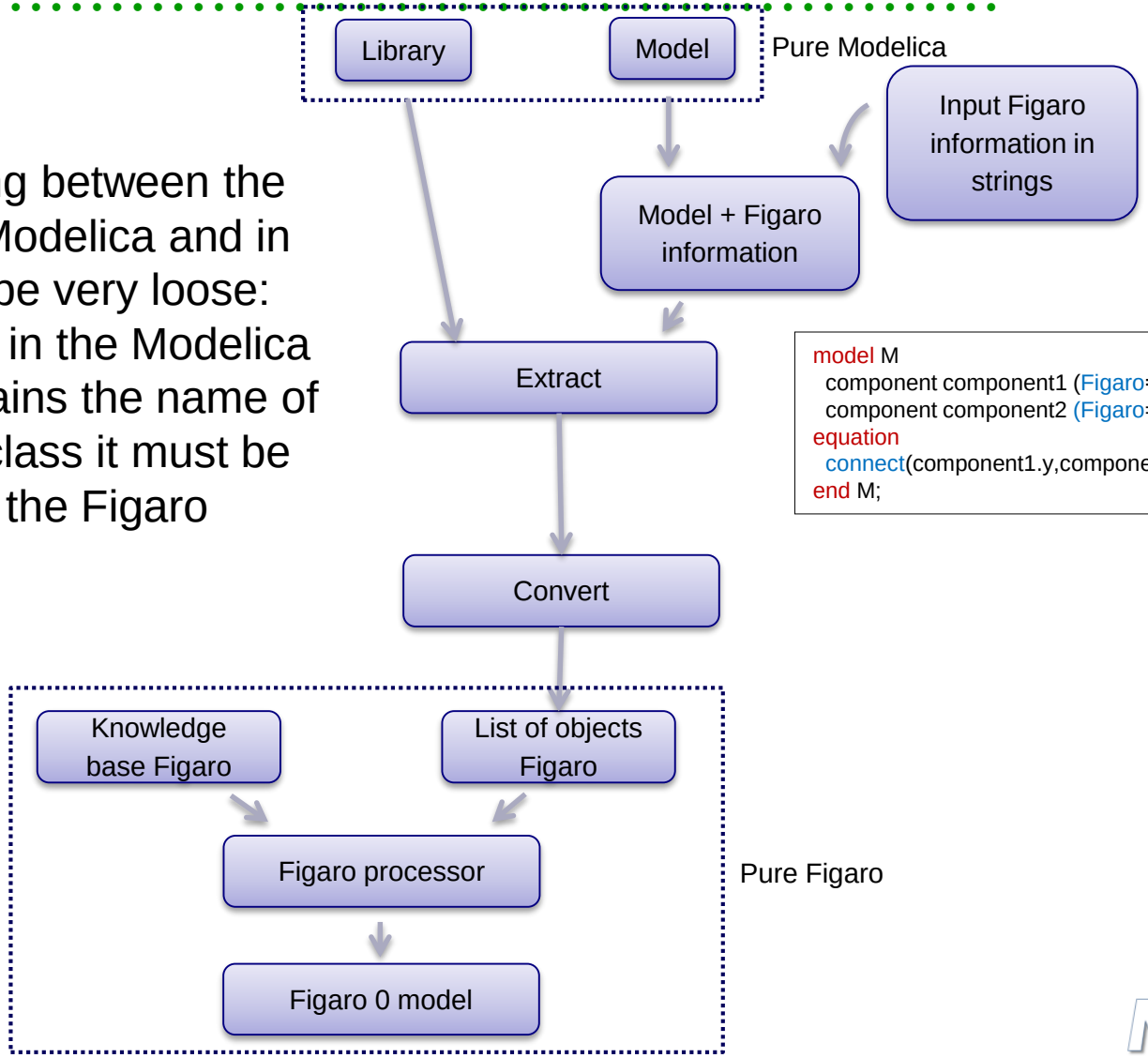
Simulation



Modelica Library

Using Modelica in conjunction with the Figaro tools (the binding principle)

The mapping between the classes in Modelica and in Figaro can be very loose: each object in the Modelica model contains the name of the Figaro class it must be linked to by the Figaro processor



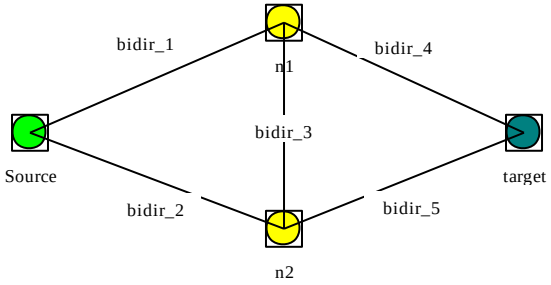
Advantages of using the Figaro language and processor

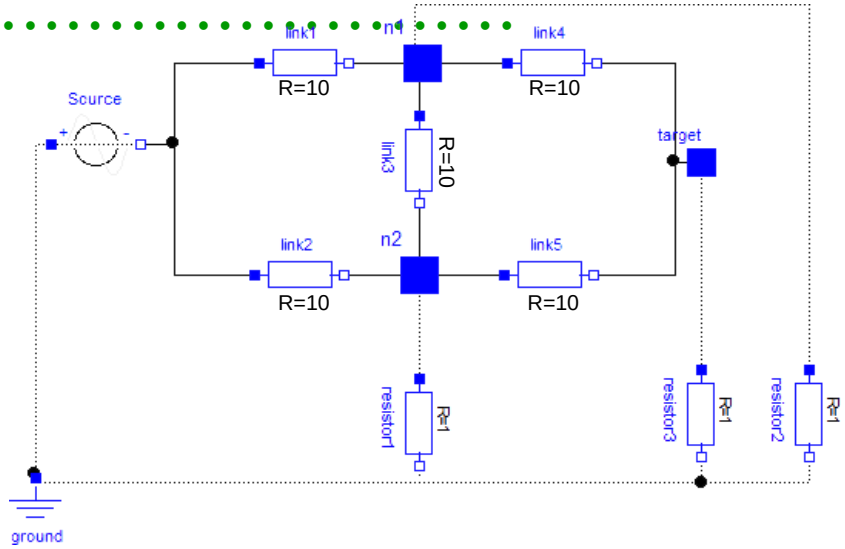
- Figaro: the first domain specific language for reliability (1990)
- Basis of the KB3 workbench: the reference tool at EDF
- Generic KB thanks to quantifiers
- Two ways to build FT
  - The CAT algorithm (Salem 1976) like most nowadays tools
  - **With macro components** => legible and structured FT
- Options to process negations (non coherent FT)
- Ability to produce correct FT for looped systems (cf. telecom example)

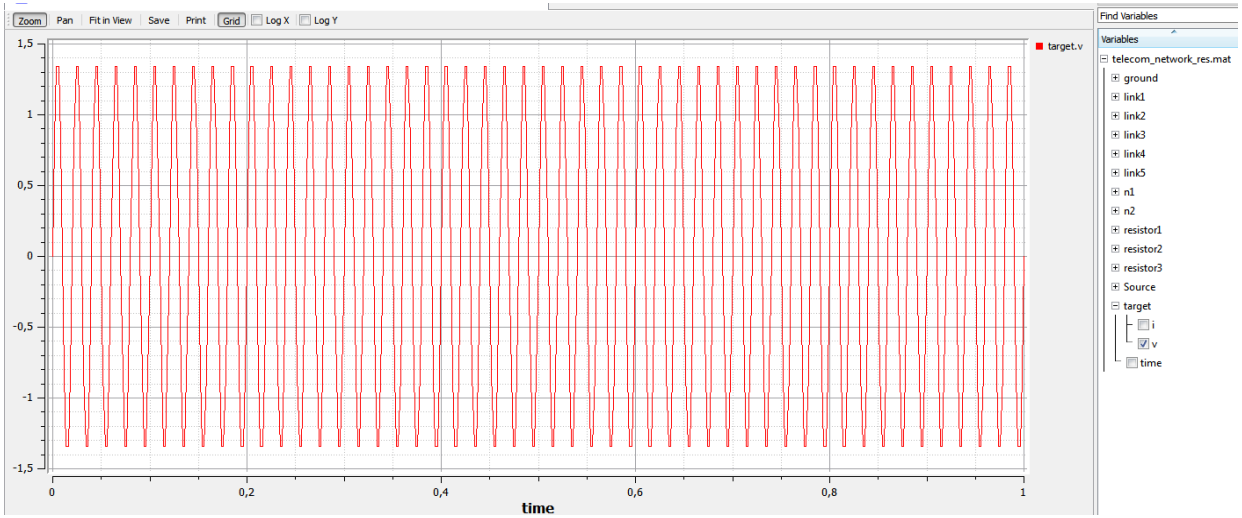
S. Salem, G.E. Apostolakis, D. Okrent : "A computer oriented approach to fault tree construction" EPRI-NP-288. 1976

Example: telecom network

Nominal mode

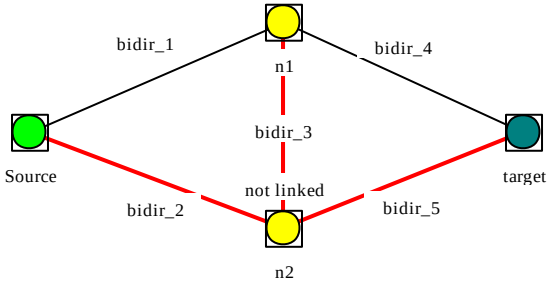


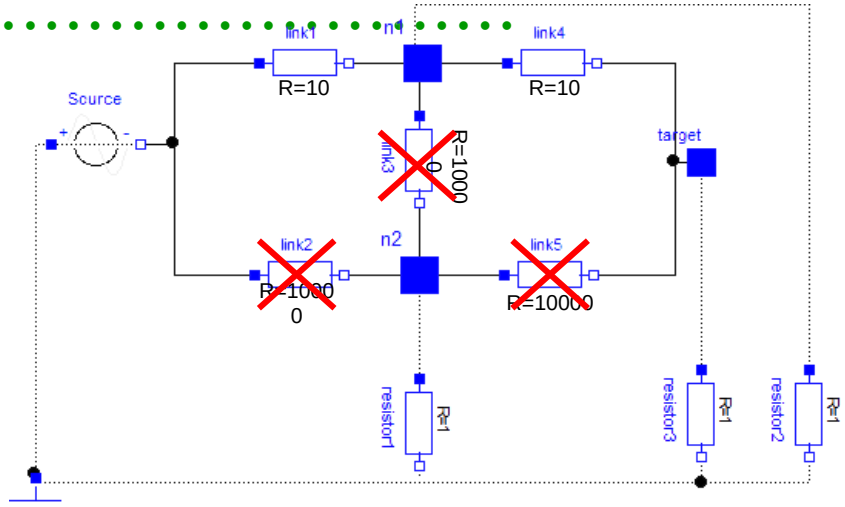




Example: telecom network

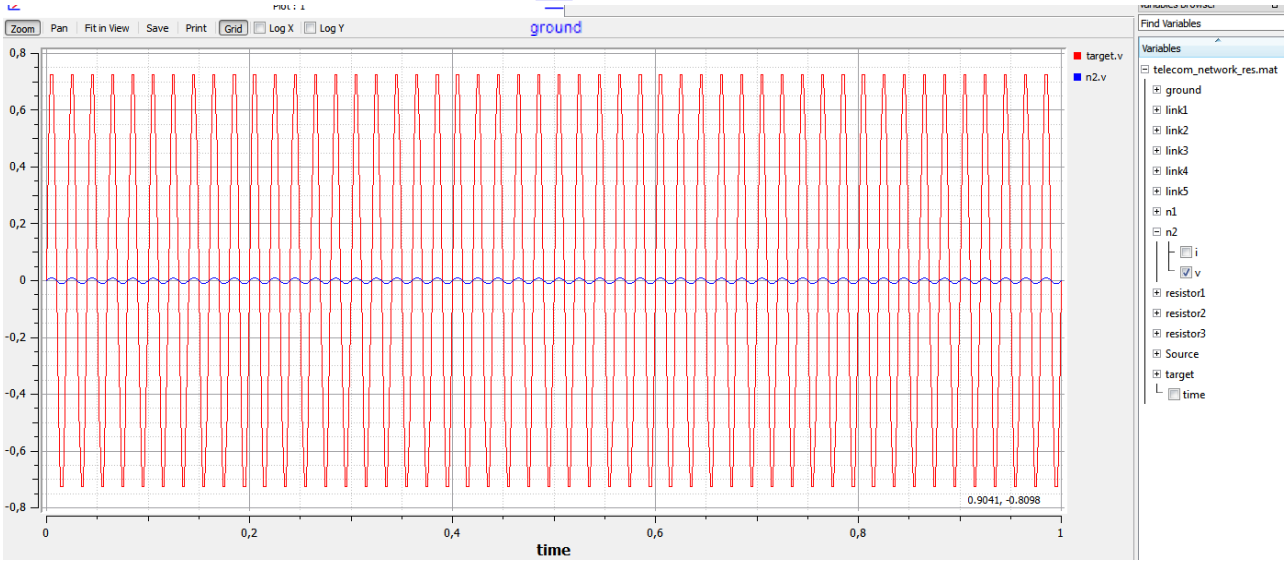
Degraded mode





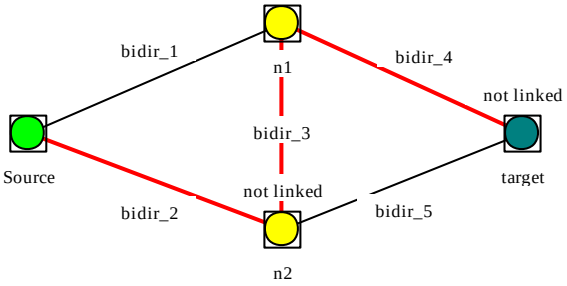
target.v

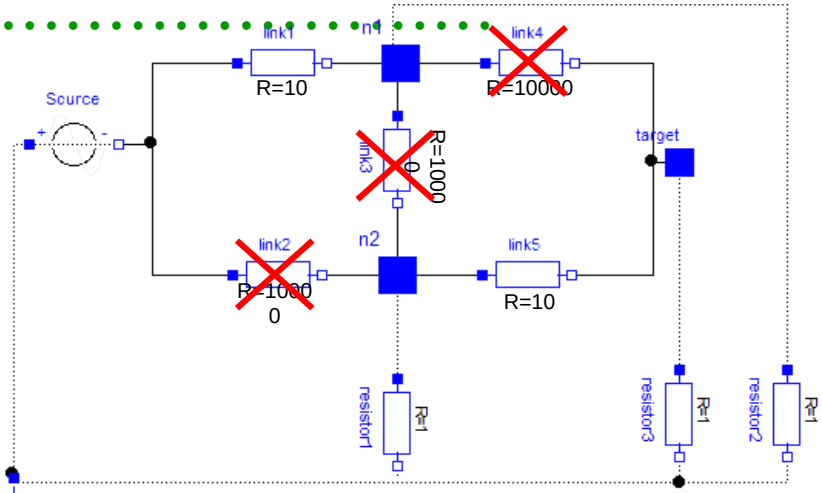
n2.v



Example: telecom network

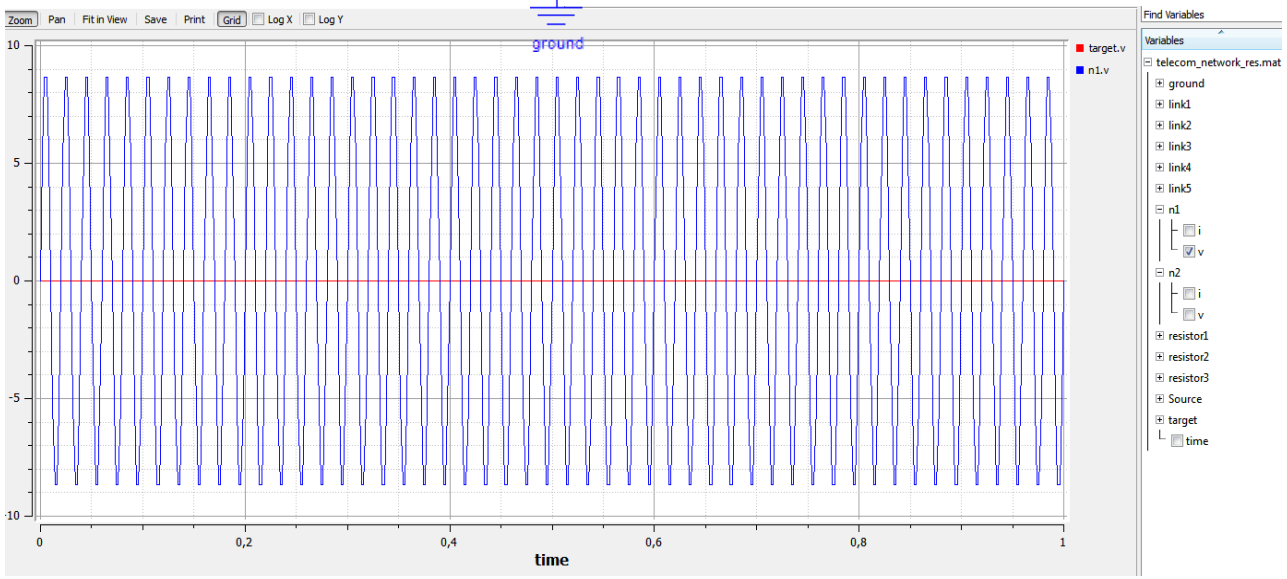
Failure of the mission





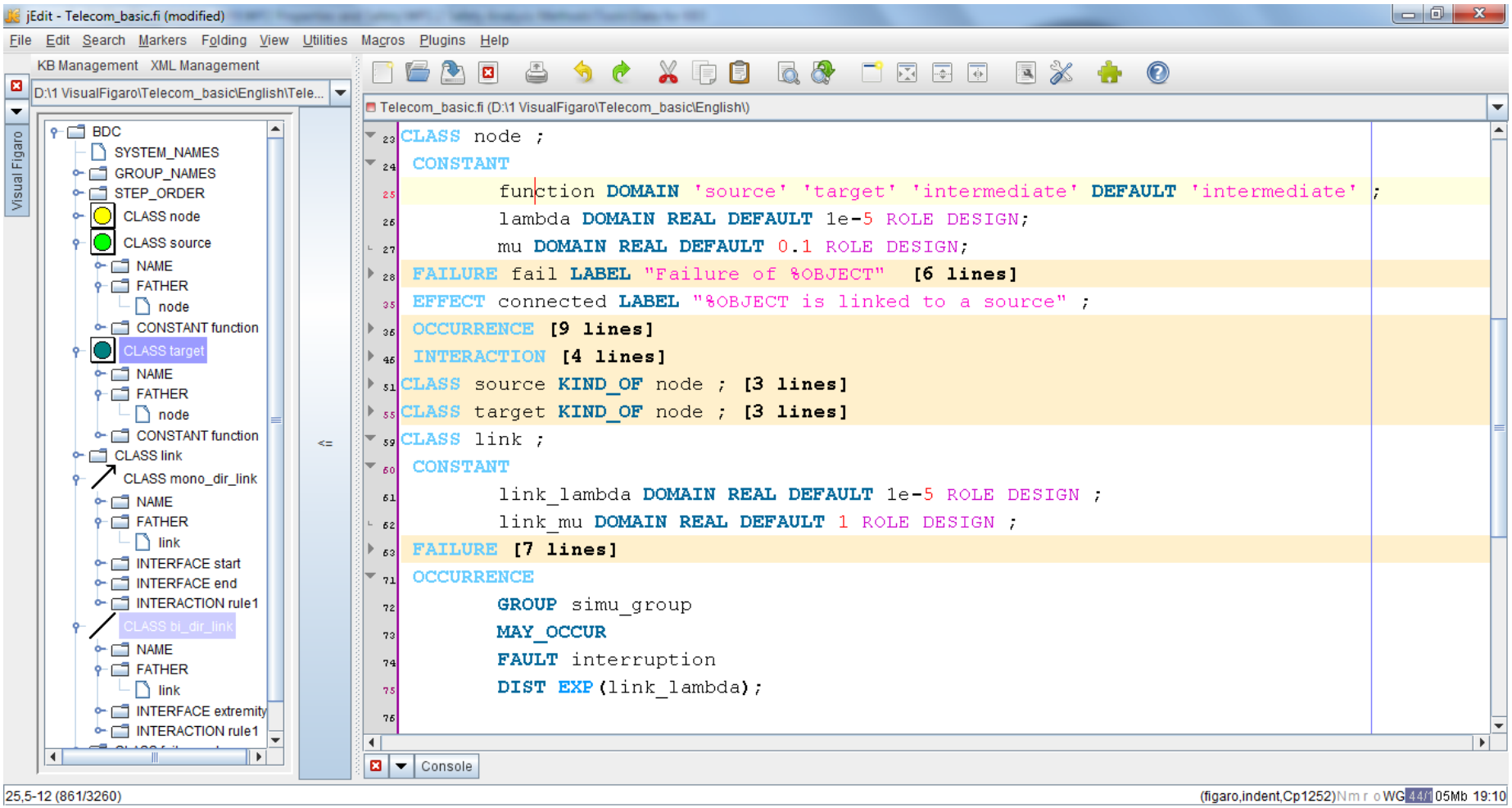
n1.v

target.v



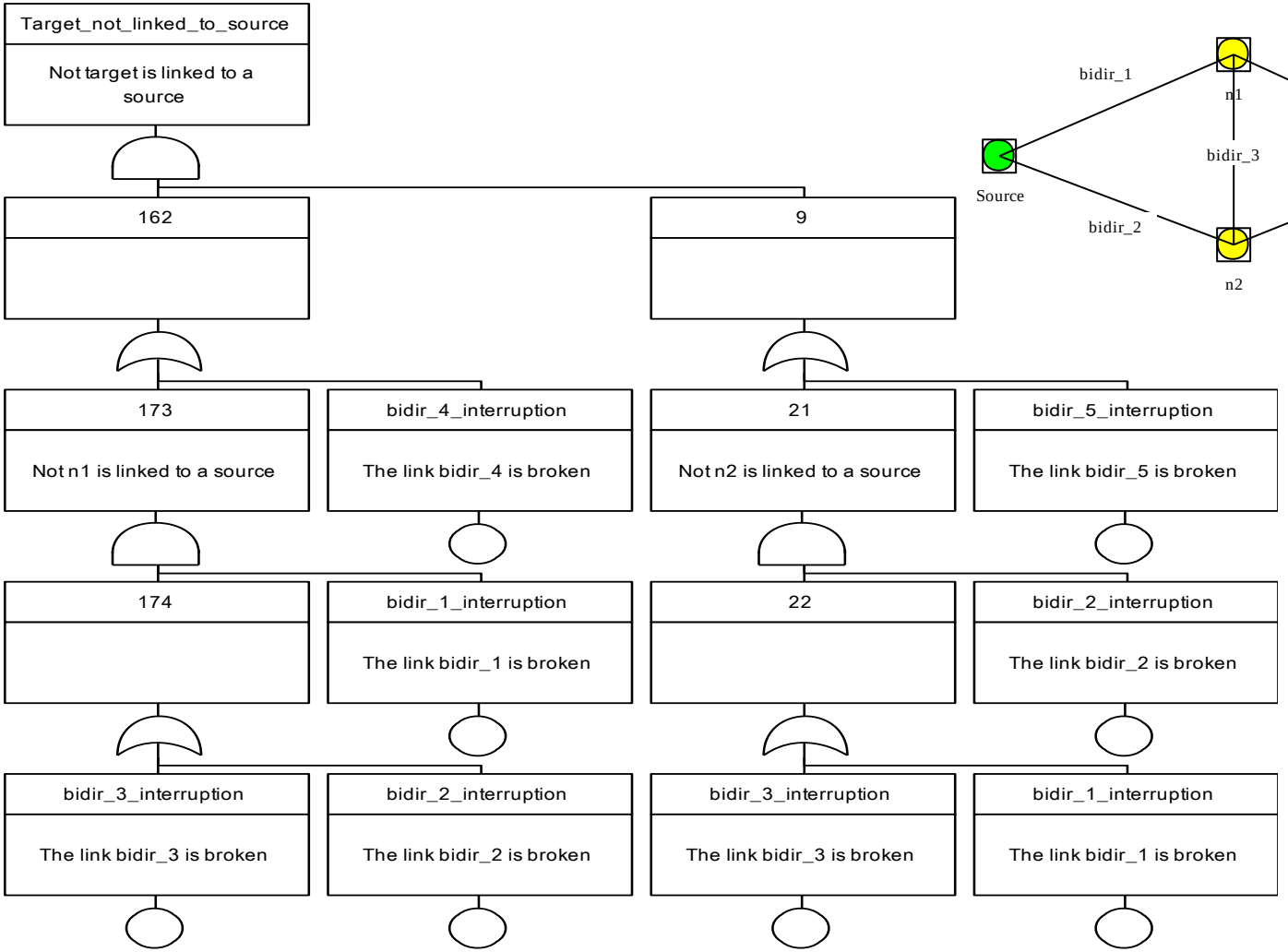
We want to get the exhaustive list of minimal cut sets, without trying all combinations of failures in Modelica!

Telecom network: the FIGARO library



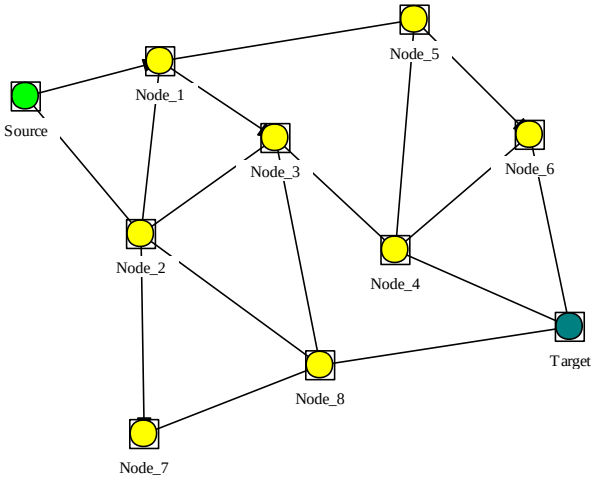
The library is edited in the Visual Figaro editor
Total length: 115 lines

Example: telecom network
Fault tree generated by the FIGARO processor

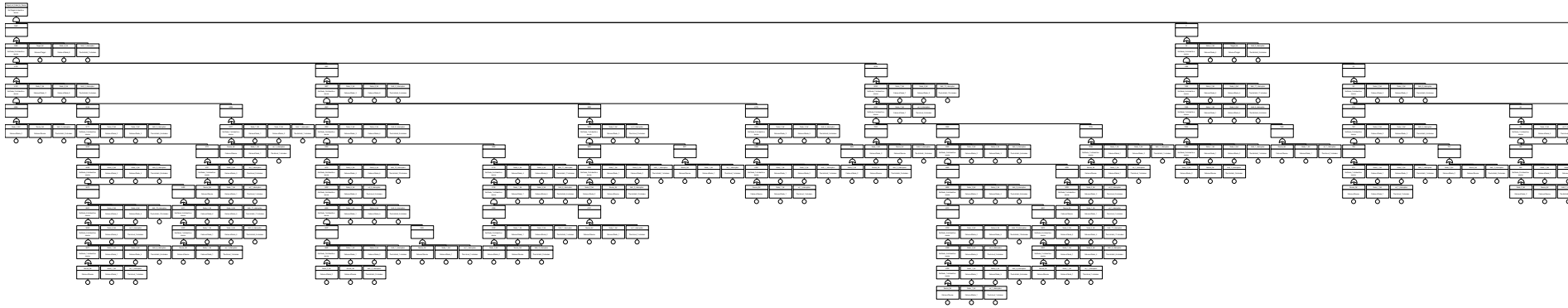


(considering nodes as perfect to get a small fault tree)

It could also work for a more complicated case…



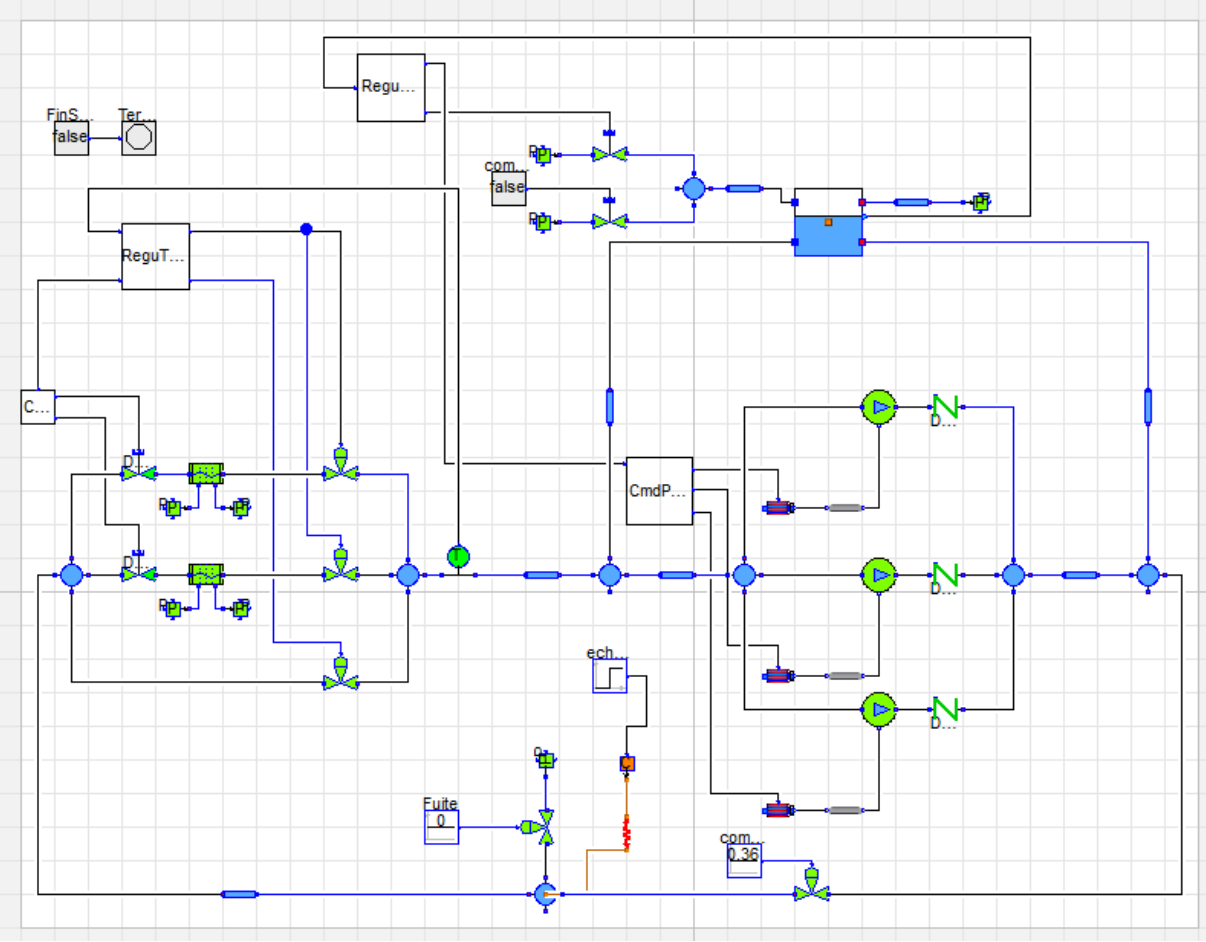
Generation of a fault tree eliminating loops by KB3 (failures of nodes and links taken into account)



First third of the fault tree…

Example 2: thermohydraulic system (SRI)

- Real use case of MODRIO
- Cooling system in a nuclear power plant



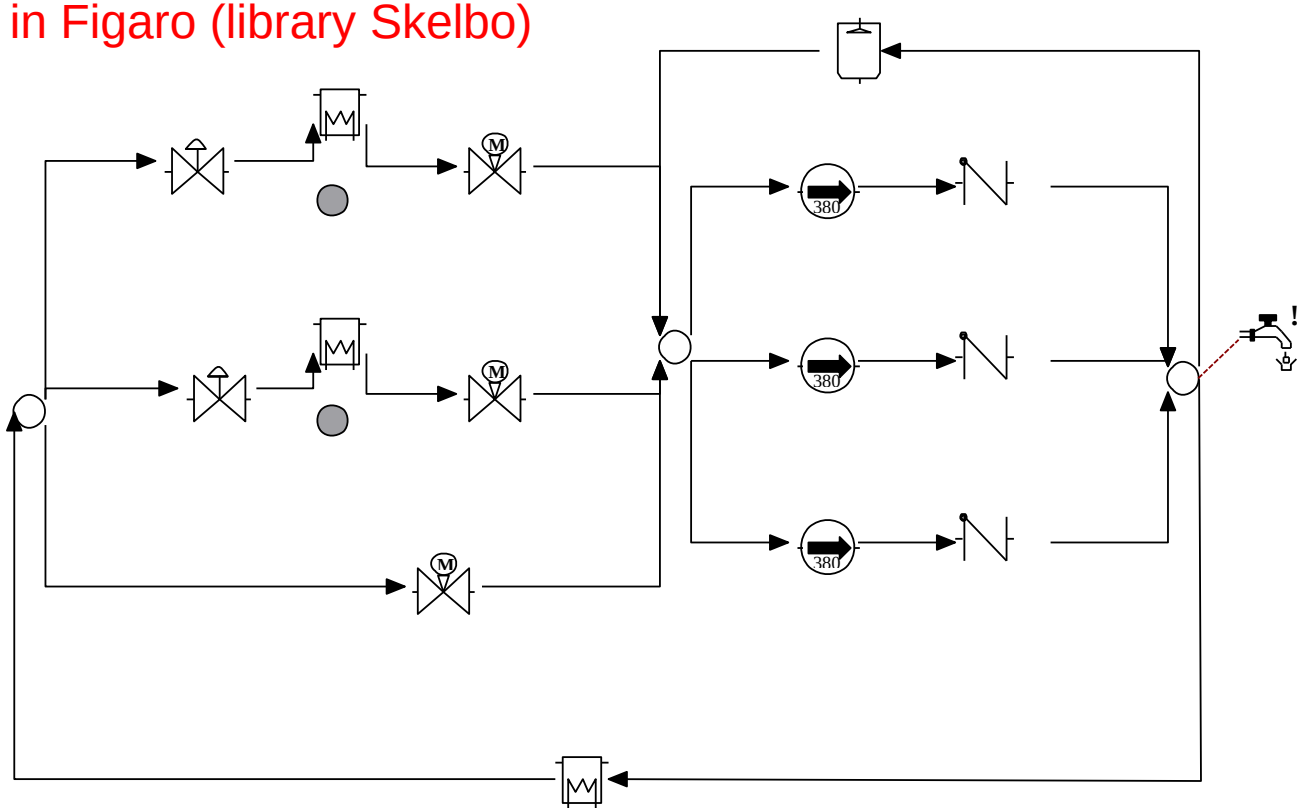
SRI in Modelica
(library ThermosysPro)

The SRI as it would be input in KB3

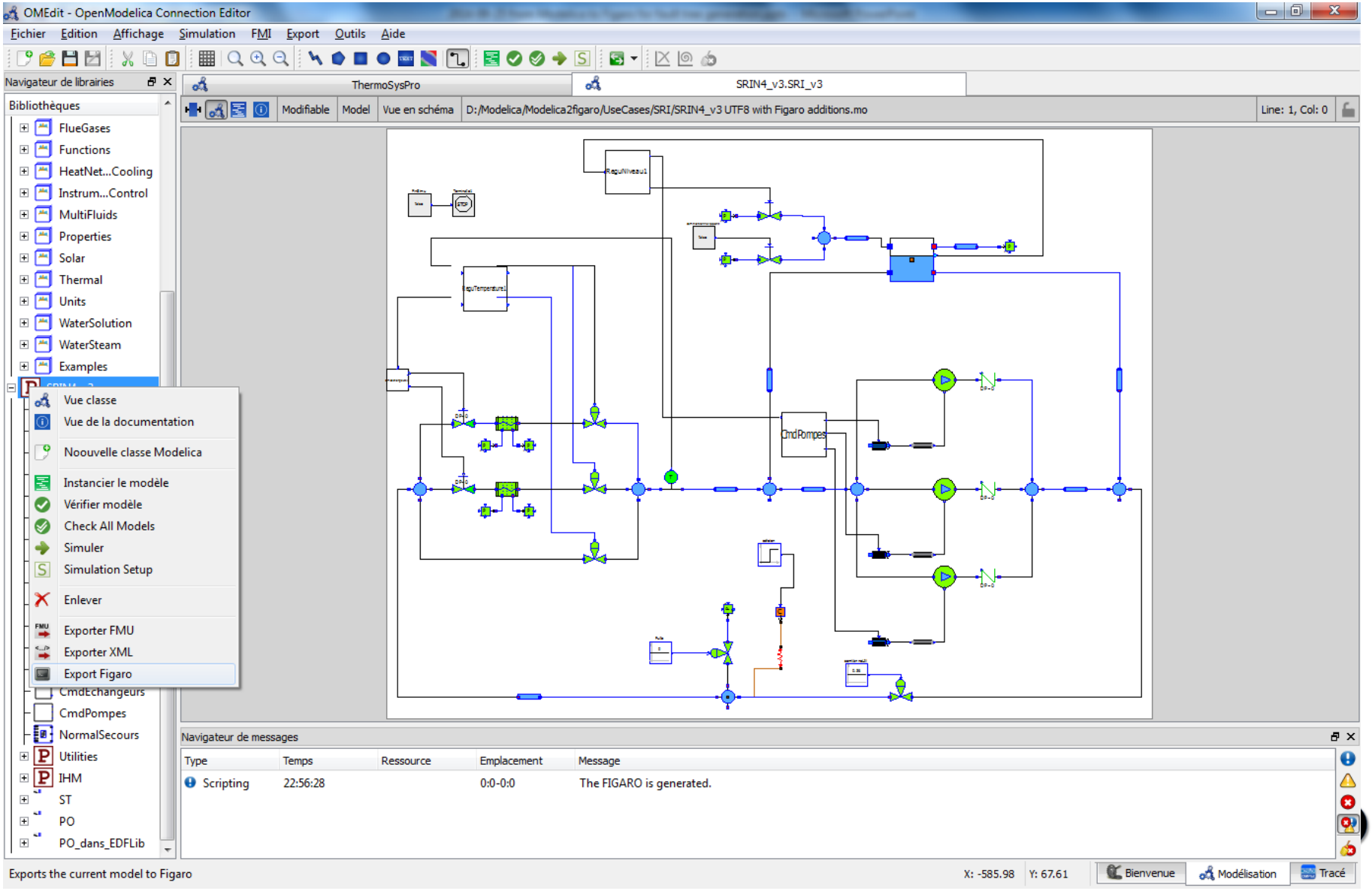
- The Figaro library (Skelbo) was developed long ago, independently from the SRI model in Modelica

In fact, the same topological information is input in the Modelica model

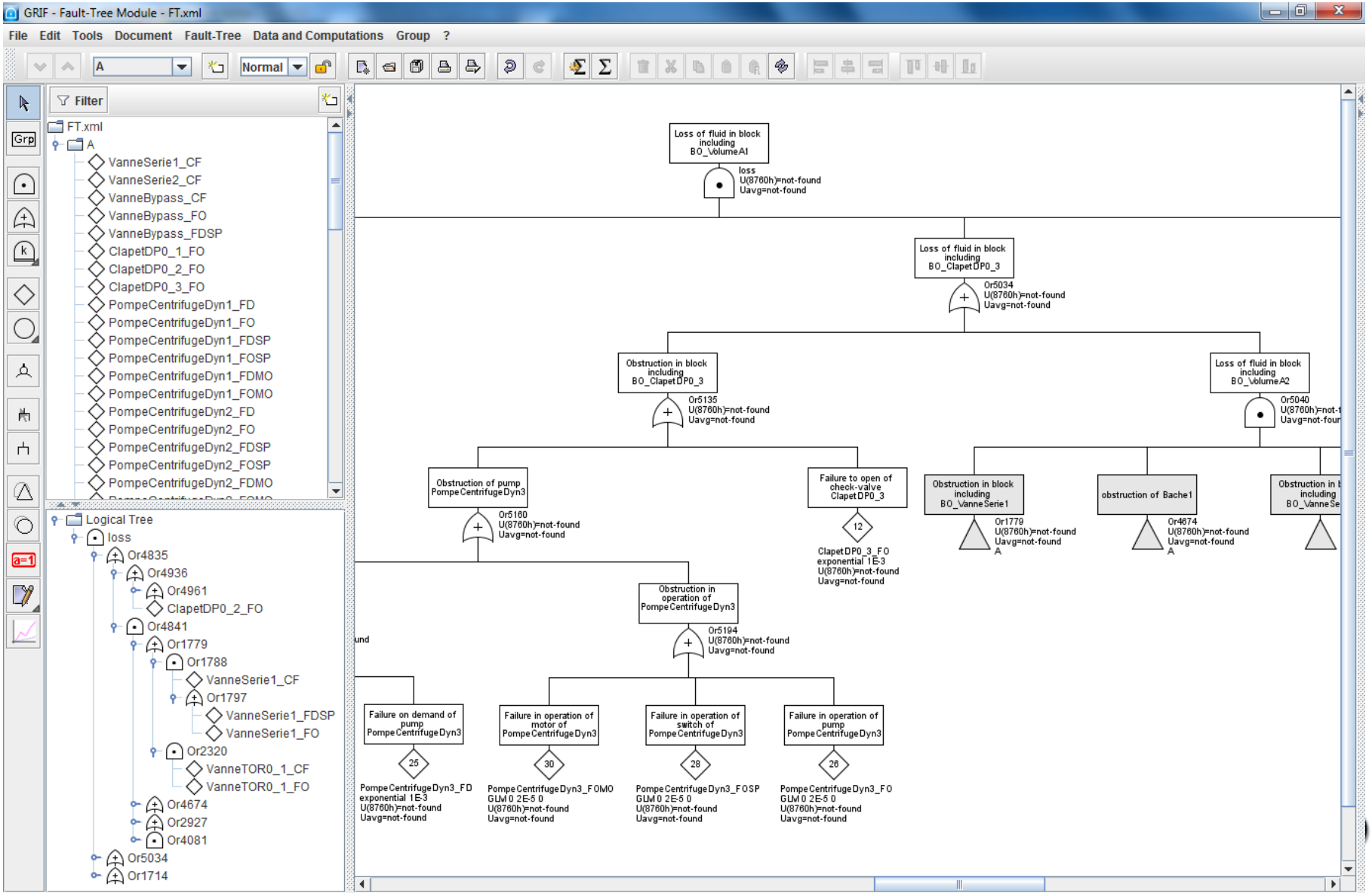
SRI in Figaro (library Skelbo)



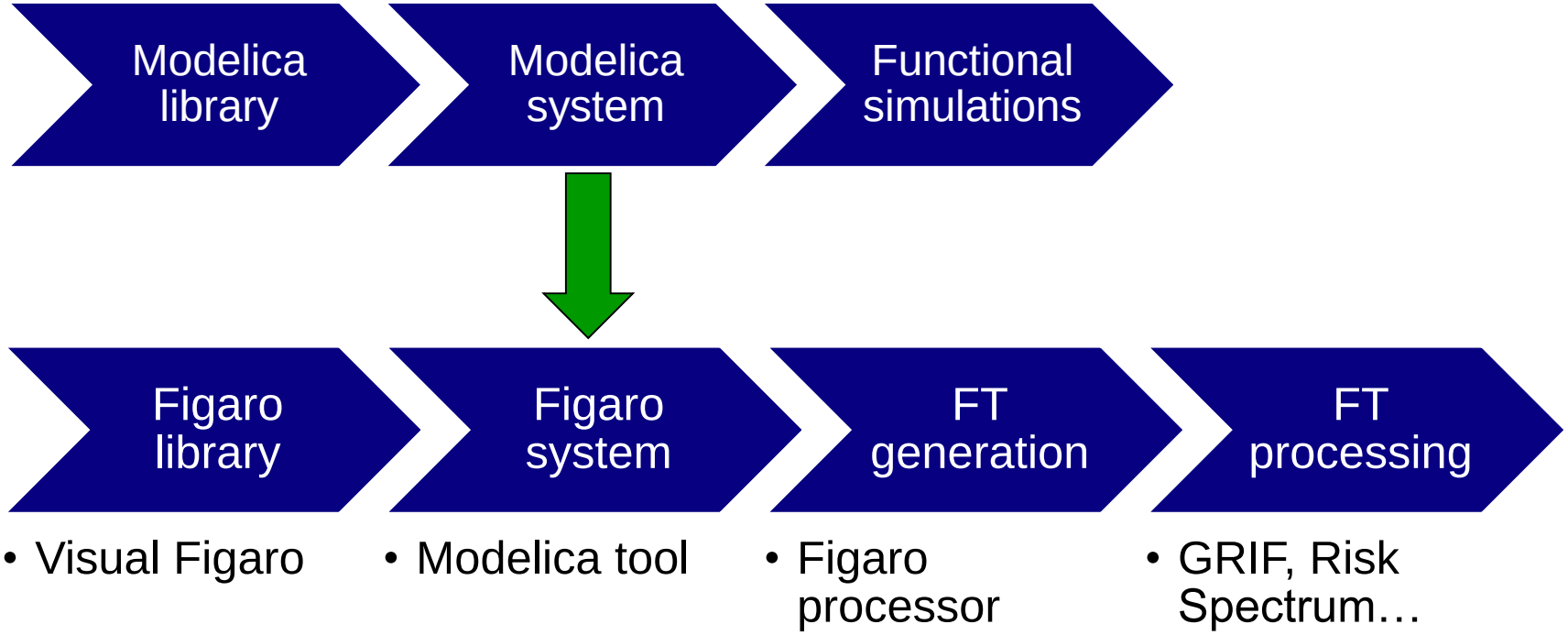
Demonstration: OpenModelica



The generated fault tree in the GRIF editor



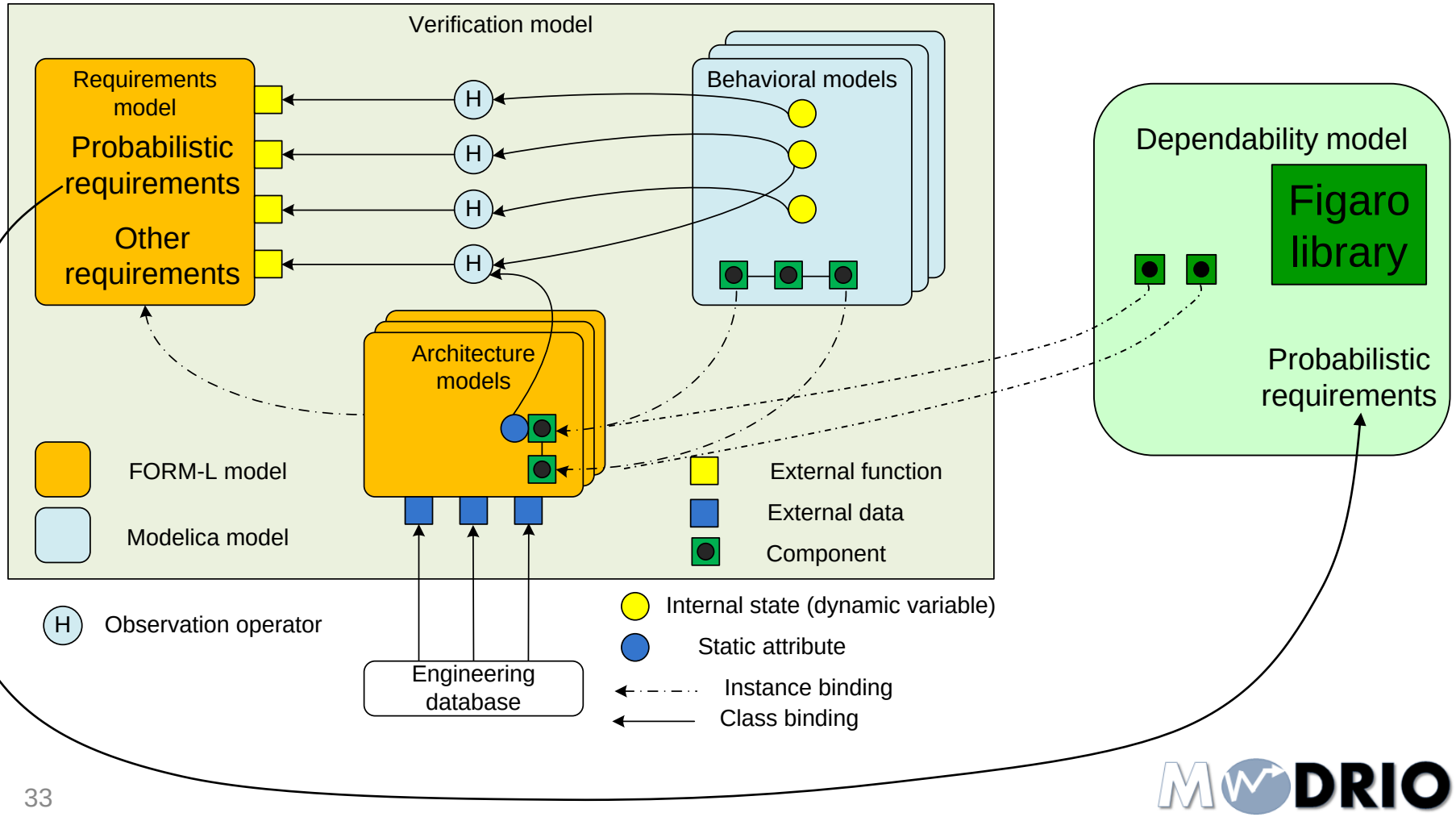
Summary: engineering workflow



Conclusion of Part 2

- Main advantage of this approach: relies on mature tools and formalisms
- Smart fault tree generator
  - Can use automatically generated macro components
  - Handles looped systems properly
- No need to change the Modelica model, nor the Figaro library
- The Figaro and Modelica parts are loosely coupled: no need to have a bijection between the elements of the two models
- It will be possible to propose an enhanced GUI to help the user input correct Figaro additions (with pull down menus…)

Perspective: binding the Figaro model to Form-L models



THANK YOU!

Where to find more information on tools:

http://openmodelica.org download OpenModelica with Figaro text-only tools

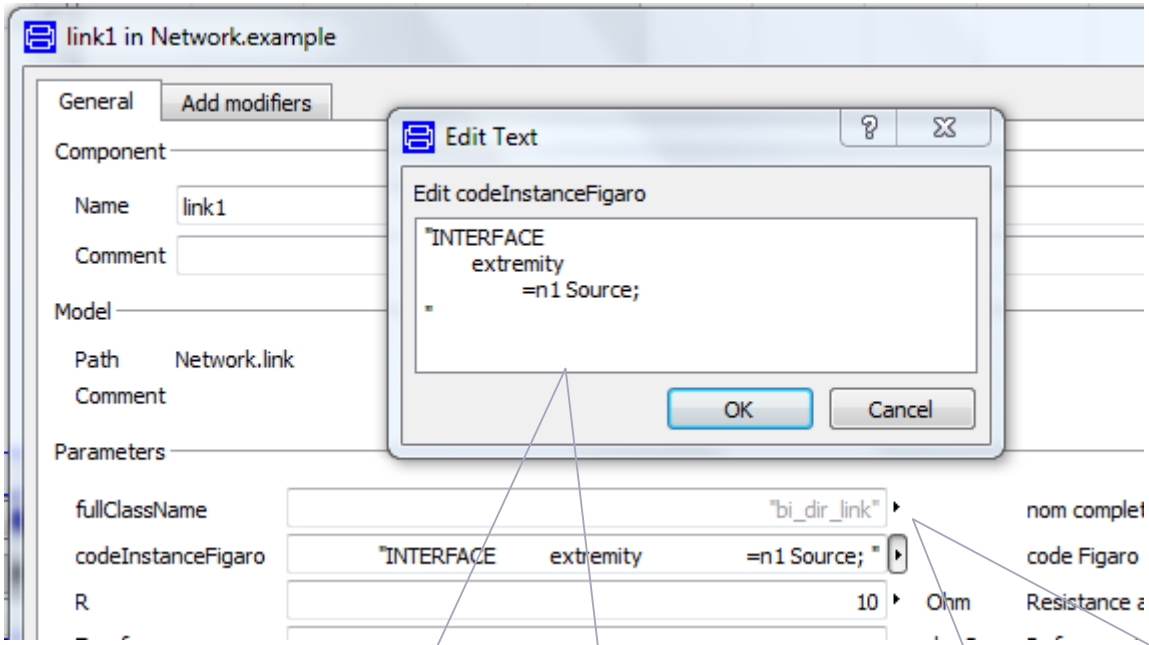
http://sourceforge.net/projects/visualfigaro/ download KB3 and other Figaro based tools

http://marc.bouissou.free.fr/ papers on the principles of Figaro tools

http://rdsoft.edf.fr then link to KB3: general information on KB3

COMPLEMENTS

Telecom network: the FIGARO information that must be added in the Modelica model



In the Modelica model, the class "link" is a subclass of:

- The electrical component resistor
- The generic class FIGARO that contains only two string parameters A and B

A: The only Figaro code the user has to input (for every link)

B: The name of the corresponding class in the FIGARO library is defined in the class "link"

Limitations of the CAT algorithm

3. CRITICISM OF THE CAT ALGORITHM

Let us consider a simple but useful example for the following discussions. Let us analyze a circuit composed of a series of three resistors (Fig. 2)

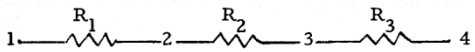


Figure 2

In particular we will analyze those failures causing the current loss at point 3. CAT models as presented in [1] will be used. Since this problem is essentially related to the existence of a signal in a particular point of the circuit, the choice will be of "current type".

Therefore, as the current flows from node 1 to node 4, the i-th resistor simplified model will be as follows:

I_i	SR_i	I_{i+1}
0	-	0
-	1	0
1	-	1

where - = don't care state
I_i = current at i-th node (0 = no current)
SR_i = state of i-th resistor
SR_i = 0 resistor good, 1 resistor failed

With orientation from left to right, in the generated FT for I_3=0, R_3 does not appear

With the macro component approach of KB3, the model states:
- failure of R_i => failure of MC
- failure of MC => I_i = 0

G. Squellati "Critical review of the CAT algorithms for automated fault tree construction". JRC technical note N° 1.06.01.80.84. October 1980